# Laplacians on discrete and quantum geometries

# Gianluca Calcagni, Daniele Oriti, Johannes Thürigen

Max Planck Institute for Gravitational Physics (Albert Einstein Institute) Am Mühlenberg 1, D-14476 Potsdam, Germany E-mail: calcagni@aei.mpg.de, doriti@aei.mpg.de, johannes.thuerigen@aei.mpg.de

ABSTRACT: We extend discrete calculus to a bra-ket formalism for arbitrary (*p*-form) fields on discrete geometries, based on cellular complexes. We then provide a general definition of discrete Laplacian using both the primal cellular complex and its topological dual. The precise implementation of geometric volume factors is not unique and comparing the definition with a circumcentric and a barycentric dual we argue that the latter is, in general, more appropriate because it induces a Laplacian with more desirable properties. We give the expression of the discrete Laplacian in several different sets of geometric variables, suitable for computations in different quantum gravity formalisms. Furthermore, we investigate the possibility of transforming from position to momentum space for scalar fields, thus setting the stage for the calculation of heat kernel and spectral dimension in discrete quantum geometries.

**KEYWORDS:** Models of Quantum Gravity, Lattice Models of Gravity

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## 1 Introduction

In a variety of current approaches to quantum gravity, including loop quantum gravity (LQG) [1, 2] and spin-foam models [3–5], group field theory [6, 7], simplicial quantum gravity, be it quantum Regge calculus [8] or (causal) dynamical triangulations [9], the basic building blocks of geometry and spacetime are discrete in nature. Depending on the specific theory considered, these discrete building blocks can be interpreted as the true degrees of freedom of quantum spacetime (it is the case in loop gravity and spin-foams, as well as in group field theory) or as a convenient regularization (in simplicial gravities) chosen only for the purpose of defining the theory or being able to calculate with it. In any case, one is left with the task of reconstructing a continuum spacetime and its geometry starting from such discrete structures (on which one can make appropriate superpositions of states, in canonical setting, or define histories, in path-integral-like frameworks). Despite a wealth of results obtained in recent years in all these approaches, the issue of recovering continuum geometry from discrete structures, or more generally that of extracting geometric information from them, remains outstanding.<sup>1</sup> Notice also that the issue of determining the effective geometry in a given regime is present also in continuum frameworks like asymptotic safety [11], simply because one allows for quantum fluctuations between continuum geometric configurations.

One difficulty has to do with the limited number of geometric observables being available and under control in all these scenarios at the quantum level, where it is clear that the only meaningful notion of effective geometry is in terms of the evaluation of specific quantum geometric observables. In loop quantum gravity and spin-foams, for example, one has good control over the definition of areas and 3-volumes as quantum operators and over their spectrum, and definitions of length and 4-volume observables exist, but do not come with a good enough analytic control. Various distance measures exist in the simplicial context, which are usually dealt with numerically. In general, it is fair to say that much more work is needed and that the more examples of geometric observables we can construct, the more the task of analyzing the effective geometries produced in our quantum gravity models will be facilitated.

More such observables could be defined in the case of quantum gravity coupled to matter, and matter is also expected to permit the construction of *local* geometric observables (as opposed to global ones) which are still diffeomorphism invariant. Again, much on matter coupling in canonical and covariant approaches is known, even in the discrete context [12–19], but this is another area where more results are needed. One example of geometric observable that has been widely used for "reconstruction purposes", i.e., as a probe of the geometry of states, phases or histories in quantum gravity models, is the spectral dimension [20–34]. Being defined from the trace of the heat kernel, it depends on the underlying geometry through the Laplacian operator, and implicitly relies on some notion of matter field.

In this paper we focus on the notion of Laplacian in a discrete context. First of all, the Laplacian is an interesting geometric kinematical observable *per se*. Second, it is the key ingredient for the definition of momentum space and, as we mentioned, of the spectral dimension. Third, it is needed to construct coupled gravity plus matter models, as it enters the propagators for matter fields (be them scalars or gauge fields). We try to set up a general, systematic approach to its construction, which can turn out to be useful for applications [35].

The plan is the following. In sections 2 and 3 we provide a coherent framework for the definition of functions, p-form fields and differential operators on fundamentally discrete (and, later, quantum) geometries, more specifically on simplicial and cellular complexes. We base our systematic approach

 $<sup>^{1}</sup>$ A case where a continuum geometry arises naturally as a "blurring" of a discrete-symmetry structure is complexorder fractional spacetimes [10].

on the recently developed *discrete calculus* of [36, 37], that has been applied so far in the particular context of computational science [38]. We will show how it suits also our quantum gravity setting. While the formalism can be motivated as a discretization of functions on a triangulation of a given smooth manifold, we define it on abstract combinatorial complexes obeying the conditions of pseudo-manifolds, to comply with the use of such complexes in some quantum gravity approaches.

Using this, we propose (section 3) a general definition of the discrete Laplacian operator on arbitrary simplicial complexes. The definition makes use of both primal and dual complexes. We then study the properties of this Laplacian and, through them, compare different choices of dual complex (barycentric and circumcentric).

We also describe (section 4) the generalization of the same operator to simplicial pseudomanifolds with boundaries and arbitrary cellular complexes, and the notion of momentum transform in terms of eigenfunctions of the Laplacian, that plays a crucial role in the calculation of the heat kernel trace, which we also discuss.

We then show (section 5) the various expressions that the newly-defined Laplacian operator takes in different choices of geometric variables, again having in mind the sets of variables currently used in various quantum gravity frameworks. This will facilitate concrete applications and computations [35]. As already mentioned, the setting is chosen as general as possible. In particular, complexes are defined only combinatorially in order to be applicable to diverse theories of quantum geometry at a second stage.<sup>2</sup> We give detailed expressions for the usual edge-length Regge calculus as well as for its first order versions (face normal-connection, flux-connection and area-angle). Flux and area-angle variables are directly useful also in the context of LQG spin networks, spin-foams and group field theory. Causal dynamical triangulations are the special case of globally constant volumes and, as such, they are also contained in this formalism.

We conclude with an outlook on the quantization of the Laplacian operator in a quantum geometry context, and on its explicit evaluation in quantum gravity models, pointing out the difficulties that arise there.

## 2 A bra-ket formalism for discrete position spaces

In order to define a Laplacian operator, we need to have at our disposal a notion of fields, and more generally *p*-forms, in a discrete setting. Moreover, such fields have to be *localized* in a suitable sense, as we are dealing with a local operator and we would like to capture, through it, the local properties of the discrete geometry. In the following we will explain the formalism in detail. For now, we just highlight the main ideas.

At a conceptual level, as mentioned, we need some generalization of a "field at a point" in order to be able to define the action of the Laplacian on it. It is well known, in general, that for fields in the continuum the notion of position basis (exactly localized state) is unavailable. As we will see, the only existing inner product for p-forms involves an average (smearing) over an extended region of space. This smearing is also needed for the very definition of field theories in the continuum [42]. What can be defined, in principle, is instead a basis of states restricted to a subregion of the pseudo-manifold. We will not discuss this construction in the continuum, but we will use the natural analogue of this smearing in the discrete case to define a position basis and a bra-ket formalism for discrete p-forms.

From a more mathematical point of view, the definition of such basis takes the need for smearing into account together with several other structures (dualities) in both continuum and discrete geometry. In fact, the crucial point of the construction is a unification of four kinds of dualities: 1)

<sup>&</sup>lt;sup>2</sup>This is the type of complexes arising, for example, in group field theory [6, 7, 39-41], spin-foam models and loop quantum gravity [3-5].

the bra-ket duality of usual quantum mechanics in continuum position space, 2) Hodge duality on continuum Riemannian manifolds, 3) the duality of chains and cochains on complexes, and finally 4) the discrete counterpart of Hodge duality constructed from the combinatorial complex and its dual. All these dualities are well known but we will take advantage of them in a novel way.

#### 2.1 Two dualities in the continuum

We start with two dualities in the continuum. The setting is thus that of a smooth manifold. Remaining in the continuum, there is no good way to unify these dualities in a strictly local manner (i.e., there is no such thing as a position basis), but a unification will be possible for their discrete analogs (the smearing being built in the discrete setting).

1) First, we have the duality of states  $\phi$  in the Dirac formalism of quantum mechanics as bras and kets [43],

$$\langle \phi | \longleftrightarrow | \phi \rangle,$$
 (2.1)

where  $|\phi\rangle$  is a vector in a complex Hilbert space  $\mathcal{H}$  and  $\langle \phi |$  is its covector, i.e., its dual linear form on  $\mathcal{H}$  with respect to the inner product  $\langle \cdot | \cdot \rangle$  of  $\mathcal{H}$  (which uniquely exists according to the Riesz representation theorem). The duality is an isometric anti-isomorphism: it preserves the norm and is linear up to complex conjugation of scalar factors.

Later we will be interested in function spaces, and in the discrete counterpart of position space. For single particles (where by definition localization is possible), one has a complete orthonormal (continuum) position basis  $\{|x\rangle\}$ ,

$$\langle x|y\rangle = \delta(x,y),$$
  
$$\int \mathrm{d}^d x \, |x\rangle \langle x| = \mathbb{1}$$

The Hilbert space  $\mathcal{H}$  of such system can be identified with the square integrable complexvalued functions  $L^2(\mathbb{R}^d, \mathbb{C})$  with inner product

$$\langle \phi | \psi \rangle = \langle \phi | \int_{M} \mathrm{d}^{d} x \, | x \rangle \langle x | \psi \rangle = \int_{M} \mathrm{d}^{d} x \, \phi_{x} \psi_{x}^{*} \,, \tag{2.2}$$

where  $\phi_x := \langle \phi | x \rangle$  are the position basis coefficients. Thus, at the level of these position functions the duality is just given by complex conjugation,

$$\phi_x = \langle \phi | x \rangle \quad \longleftrightarrow \quad \langle x | \phi \rangle = \phi_x^* \,, \tag{2.3}$$

because of its anti-linearity.

In the following we are not particularly interested in quantum mechanics but rather in a convenient notation for elements in  $L^2$  function spaces for (*p*-form) fields.

2) Second, on a (continuum) Riemannian manifold (M, g) there is Hodge duality which maps p-forms  $\phi \in \Omega^p(M)$  to (d-p)-forms  $*\phi \in \Omega^{d-p}(M)$  [44],

$$\phi = \phi_{i_1 \dots i_p} \mathrm{d} x^{i_1} \wedge \dots \wedge \mathrm{d} x^{i_p} \quad \longleftrightarrow \quad *\phi = (*\phi)_{i_{p+1} \dots i_d} \mathrm{d} x^{i_{p+1}} \wedge \dots \wedge \mathrm{d} x^{i_d} \,, \tag{2.4}$$

with coefficients

$$\phi_{i_1\dots i_p} \quad \longleftrightarrow \quad (*\phi)_{i_{p+1}\dots i_d} = \frac{\sqrt{g}}{(d-p)!} \epsilon_{i_1\dots i_d} g^{i_1 j_1} \dots g^{i_p j_p} \phi_{i_1\dots i_p} \,. \tag{2.5}$$

In general it is a duality only up to a sign,  $**\phi = (-1)^{p(d-p)}\phi^3$ . The natural inner product of *p*-forms is again a position manifold integration by pairing a form and a dual form,

$$(\phi,\psi) = \int_M \phi \wedge *\psi = \int_M \left(\phi_{i_1\dots i_p}\right)_x \left[(*\psi)_{i_{p+1}\dots i_d}\right]_x \sqrt{g_x} \mathrm{d}x^{i_1} \wedge \dots \wedge \mathrm{d}x^{i_d} \,. \tag{2.6}$$

This defines a  $L^2$ -space of forms  $L^2\Omega^p(M)$  [45].

The crucial point to notice is that this natural inner product, compatible with the tensorial (*p*-form) nature of the fields, involves an averaging (smearing) over the base manifold. Because of this, a simple-minded notion of a position basis is not viable, as any perfectly localized field would not be well-defined an element of the above space. Only smeared fields are. We will see how the discrete setting provides a natural notion of smearing, which in turn allows to define an analogue of a position basis even for fields.

## 2.2 Exterior forms on simplicial complexes

One can identify a natural concept of *discrete forms* by using a third type of duality. For defining it, we choose finite abstract simplicial complexes as our discrete setting.

A finite abstract simplicial complex K (in the following, simplicial complex for short) is a multiset of ordered subsets  $\sigma$  of the set of vertices  $K_0 = \{v_1, v_2, \ldots, v_{N_0}\}$  such that if  $\sigma \in K$  and  $\sigma' \subset \sigma$  also  $\sigma' \in K$  [46]. In general,  $\sigma' \subset \sigma$  is called a face of  $\sigma$ . All subsets of cardinality p + 1are called *p*-simplices  $\sigma_p \in K_p$  and the dimension d of K is defined as the maximal cardinality of simplices in K. Thus K consists of 0-simplices to d-simplices,  $K = \bigcup_{p=0}^{d} K_p$ , and is also referred to as a simplicial d-complex. The ordering of the sets  $\sigma_p = (v_{i_1}, \ldots, v_{i_p}) =: (i_1 \ldots i_p)$  defines an orientation on the complex.

3) There is a duality between chains and cochains on the simplicial complex K [46]. Formal linear combinations of *p*-simplices generate the finite vector space of *p*-chains  $c \in C_p(K)$  (which we take on  $\mathbb{C}$ ) and we introduce a bra-ket notation to write them as

$$c\rangle = \sum_{\sigma_p \in K_p} c_{\sigma_p} |\sigma_p\rangle = \sum_{\sigma_p \in K_p} \langle \sigma_p | c \rangle |\sigma_p\rangle.$$
(2.7)

Accordingly, linear forms on chains are called *p*-cochains  $\tilde{c} \in C^p(K)$ . As they can be expanded in the dual basis  $\{\langle \sigma_p | \}$ , defined by the pairing  $\langle \sigma_p | \sigma'_p \rangle = \delta_{\sigma\sigma'}$ , the cochain  $\tilde{c}$  dual to c can be written as the bra

$$\langle \tilde{c} | \equiv \langle c | = \sum_{\sigma_p \in K_p} c^*_{\sigma_p} \langle \sigma_p | = \sum_{\sigma_p \in K_p} \langle c | \sigma_p \rangle \langle \sigma_p | .$$

$$(2.8)$$

The connection to the first two continuum dualities is the following [36, 38]: On a finite triangulation of a Riemannian manifold (M, g) with combinatorial structure K, p-cochains can be naturally interpreted as discretized p-forms  $\phi \in \Omega^p(K) \cong C^p(K)$  by smearing the continuous form  $\phi_{\text{cont}} \in$  $\Omega^p(M)$  over p-surfaces S represented by chains  $|S\rangle = \sum_i V_{\sigma_n^i} |\sigma_p^i\rangle \in C_p(K)$  in the triangulation:

$$\phi(\mathcal{S}) := \langle \phi | \mathcal{S} \rangle = \sum_{i} V_{\sigma_p^i} \left\langle \phi | \sigma_p^i \right\rangle =: \sum_{i} V_{\sigma_p^i} \phi_{\sigma_p^i} \sim \sum_{i} \int_{\sigma_p^i} \phi_{\text{cont}} = \int_{\mathcal{S}} \phi_{\text{cont}} , \qquad (2.9)$$

where  $V_{\sigma_p}$  denotes the *p*-volume of  $\sigma_p$ . In particular, for a single *p*-simplex surface  $S = \sigma_p$  represented by  $V_{\sigma_p} | \sigma_p \rangle$  one has

$$\phi(\sigma_p) = V_{\sigma_p} \langle \phi | \sigma_p \rangle = V_{\sigma_p} \phi_{\sigma_p} \sim \int_{\sigma_p} \phi_{\text{cont}}.$$
(2.10)

 $<sup>^{3}</sup>$ For Lorentzian manifolds there is an extra minus sign; this fact would be an important guiding line for extending the discrete formalism consistently to Lorentzian geometries.

Therefore, the coefficient  $\phi_{\sigma_p} = \langle \phi | \sigma_p \rangle$  can be interpreted as the averaged field value of  $\phi_{\text{cont}}$  over  $\sigma_p$ . Obviously, the above requires an embedding of the abstract simplicial complex into the continuum manifold.

However, note that, even though motivated by discretization, this definition works perfectly well for the abstract simplicial complex K. We just take

$$\phi_{\sigma_p} := \langle \phi | \sigma_p \rangle \tag{2.11}$$

as the definition of position coefficients of a *p*-form  $\langle \phi |$ . Even a geometric interpretation in terms of *p*-volumes  $V_{\sigma_p}$  as induced by the ambient space M in the case of triangulations is not needed at this stage, as long as we are only interested in the forms  $\langle \phi |$  themselves and not in integrated quantities  $\phi(\sigma_p)$ .

## 2.3 Choice of convention

Before moving on to discuss the other dualities and discrete calculus, let us point out one difference between our definitions and the ones that can be found in the literature [36, 38]. One has in fact a choice as to where to include the geometric information encoded in the volumes. The question is whether the *p*-volume  $V_{\sigma_p}$  of a simplex  $\sigma_p$  is defined explicitly in its *p*-chain representation  $V_{\sigma_p} |\sigma_p\rangle$ , such that

$$\langle \phi | \sigma_p \rangle = \phi_{\sigma_p} = \frac{1}{V_{\sigma_p}} \phi(\sigma_p) \tag{2.12}$$

as chosen here, or whether it is already implicit in  $|\sigma_p\rangle$  such that

$$\langle \phi | \sigma_p \rangle = \phi(\sigma_p) = V_{\sigma_p} \phi_{\sigma_p} , \qquad (2.13)$$

like in [36]. The former has the advantage that the position-space measure is explicit. The latter choice could be called the "math" convention since it is natural from the point of view of the mathematical properties of forms. This is reflected in the fact that, in this convention, Hodge duality must depend on the geometric interpretation in terms of volumes, while differentials do not [36]. In our choice, it is exactly the other way round (see eqs. (2.29) and (3.2)).

There is a third convention, used in random lattice field theory [47–49] by Itzykson [50], where  $\langle \phi | \sigma_p \rangle$  is defined as a function for every p, thus without volumes, but where the duals carry the whole *d*-volume as densities. This can be justified by the common convention in the continuum to attach the metric part  $\sqrt{g}$  of the invariant measure only to the Hodge dual forms.

#### 2.4 Discrete Hodge duality

In order to be able to define the natural scalar product for *p*-forms also for these discrete forms, a discrete version of Hodge duality is necessary. This is only possible by taking advantage of a fourth duality for simplicial pseudo-manifolds.

A finite abstract simplicial pseudo d-manifold is a finite abstract simplicial d-complex which is non-branching, strongly connected and dimensional homogeneous [39]. That is, each (d - 1)simplex is face of exactly two d-simplices (non-branching), any two d-simplices have a strong chain of d-simplices neighboring pairwise by (d - 1)-faces (strongly connected) and every simplex is face of some d-simplex (dimensional homogeneous).

4) A simplicial pseudo d-manifold K has a combinatorial dual polyhedral complex  $\star K$  consisting of (d-p)-cells  $\star \sigma_p$  (which we also denote as  $\hat{\sigma}_{d-p}$ ) dual to the primal p-simplices  $\sigma_p$ , with orientation induced from the orientation of K and cellular structure induced by the adjacency relations of K. The latter means that  $\star \sigma \subset \star \sigma'$  if, and only if,  $\sigma' \subset \sigma$ .<sup>4</sup> Then  $\star K$  can be given as a multiset over its vertex set, too.

This duality between a "primal" simplicial and a dual cell complex induces a new type of dual chains, the chains  $\star c \in C_p(\star K)$  on the dual complex. This is possible because each primal chain basis element (simplex) has a unique dual basis element. Using Dirac notation also for this duality, this reads

$$|c\rangle = \sum_{\sigma_p \in K} c_{\sigma_p} |\sigma_p\rangle \quad \stackrel{\star}{\longleftrightarrow} \quad \langle \star c| = \sum_{\sigma_p \in K} c^*_{\sigma_p} \langle \star \sigma_p| \,. \tag{2.14}$$

Note that the duality holds only up to a sign  $\star^2 = (-1)^{p(d-p)}$  [36], and also between primal and dual cochains.

Since the Hodge dual (d-p)-form cannot live on p-simplices but only on (d-p)-cells, we can regard the discrete Hodge dual of a p-form  $\phi \in \Omega^p(K)$  as its dual in the sense of this fourth duality:

$$*\phi := \star\phi \in *\Omega^p(K) \cong \Omega^{d-p}(\star K) \cong C^{d-p}(\star K) .$$
(2.15)

From the above dualities, at the level of coefficients the defining condition for the Hodge duality is the equality of the averaged field values:<sup>5</sup>

$$(*\phi)_{\star\sigma_p} := \phi^*_{\sigma_p} \,. \tag{2.16}$$

With the bra-ket convention

$$\langle \star \sigma_p | \phi \rangle = \ast \phi_{\hat{\sigma}_{d-p}} = \frac{1}{V_{\star \sigma_p}} \ast \phi(\star \sigma_p) \,, \tag{2.17}$$

this can be equivalently expressed as

$$\langle \star \sigma_p | \phi \rangle = \langle \phi | \sigma_p \rangle^* \,. \tag{2.18}$$

In the case of triangulations, we can again view the coefficients of dual fields  $*\phi$  as smeared fields:

$$*\phi(\star\sigma_p) \sim \int_{\hat{\sigma}_{d-p}} *\phi_{\text{cont}}.$$
 (2.19)

Thus, one can take Hodge duality as two different perspectives to look at the same discrete field  $\phi$ : Either as a *p*-form  $\langle \phi |$  on the primal complex or a (d-p)-form  $|\phi\rangle$  on the dual complex.

#### 2.5 Geometric interpretation of abstract complexes

So far, we have presented a formalism for fields on abstract discrete spaces without using any geometric information neither associated directly with the simplicial complex nor derived from an original continuum pseudo-manifold being discretized. However, a geometric interpretation for the elements of the simplicial complex is needed to define the inner product.

In the first place, we understand an assignment of geometry to a finite simplicial pseudomanifold K as an assignment of p-volumes  $V_{\sigma_p}$ , dual (d-p)-volumes  $V_{\hat{\sigma}_{d-p}}$  and support d-volumes  $V_{\sigma_p}^{(d)}$  to all the simplices  $\sigma_p$ . If K has a geometric realization |K| in terms of a (topological) simplicial complex over a metric space, these volumes can be induced from this realization.

While the primary volumes can be taken directly from this realization, dual and support volumes depend on how the dual complex is realized, i.e., how it is concretely constructed from (or

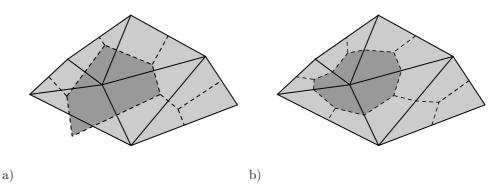


Figure 1. Circumcentric (a) and barycentric (b) dual cells to the same simplicial d = 2 complex; for the purpose of illustration dual edges are dashed and one dual 2-cell is highlighted.

embedded into) the primal complex. The most common choices are circumcentric and barycentric dual complexes (fig. 1).

For constructing the *circumcentric* dual one chooses the circumcenters of the *d*-simplices as the 0-cells and builds up higher cells (i.e., with  $p \ge 1$ ) connecting them according to the combinatorics induced from the primal complex; sub-cells of the dual complex are then automatically identified as well.

In the case of a geometric realization in terms of a Delaunay triangulation, the circumcentric dual complex is a Voronoi decomposition. A *Delaunay triangulation* is obtained by constructing d-simplices from a set of points in a metric space such that no point is in the interior of the circumsphere of any d-simplex. From the same set of points a d-cell of a *Voronoi decomposition* associated with some point P is constructed as the set of points closer to P than to any other in the set.

For this reason the circumcentric dual is often also called Voronoi dual. But this is meaningful only for Delaunay triangulations. For an arbitrary triangulation the circumcentric dual complex and the Voronoi decomposition with respect to the vertex set of the triangulation are different. In fact, the Voronoi decomposition does not have the structure of a dual complex for triangulations which are not Delaunay. This is particularly important in the abstract setting where the simplicial pseudo-manifold is considered as a gluing of d-simplices and the geometry of each is to be defined independently of its neighbors. The difference is further detailed in the discussion of the Laplacian in section 3.2 and in fig. 2 below.

The *barycentric* dual, on the other hand, is defined by a barycentric subdivision of all simplices, assumed to be flat in their interior. The barycenters of d-simplices define the dual points, and metrically connecting them iteratively to the barycenters of lower simplices defines the realization of the higher cells.

While the circumcentric dual is not built by a (circumcentric) subdivision, a simplicial subdivision nevertheless can be constructed analogously to the barycentric subdivision [36]. One can therefore in general define the support volumes  $V_{\sigma_p}^{(d)}$  to be the volume of the symmetric difference of all *d*-simplices in this subdivision having  $\sigma_p$  (or equivalently  $\star \sigma_p$ ) on its boundary.<sup>6</sup> Since the

<sup>&</sup>lt;sup>4</sup>The fact that every *p*-simplex contains  $C_{q+1}^{p+1} = \binom{p+1}{q+1}$  *q*-simplices translates into the condition for the dual complex to have  $N_{k|l} = \binom{d+1-l}{k-l} = \binom{d+1-l}{d+1-k}$  *k*-cells with a given *l*-cell as a face. This property can be used as an iterative check for constructing such dual complexes from regular graphs [51].

<sup>&</sup>lt;sup>5</sup>This is analogous to what is done in [36]. The details of the construction differ, however, since in that work the convention (2.13) is used which includes *p*-volumes.

 $<sup>^{6}</sup>$ To account also for the case of circumcentric dual complexes with some circumcenters outside their simplices, the

whole of support volumes for a given p takes all the simplices in the subdivision into account, they indeed define a space measure summing up to the total volume V of the complex,

$$\sum_{\sigma_p \in K_p} V_{\sigma_p}^{(d)} = V.$$
(2.20)

In the circumcentric case, the support volumes are not independent of the p-volumes but proportional to their product [36]:

$$V_{\sigma_p}^{(d)} = \frac{1}{d} V_{\sigma_p} V_{\hat{\sigma}_{d-p}} \,. \tag{2.21}$$

We will give explicit expressions of these volumes in terms of various geometric variables below.

#### 2.6 Inner product and position-space measure

With a well-defined meaning given to bras and kets of discrete fields, only a slight modification to the forth duality (2.14) is needed in order to have the usual geometric  $L^2$  inner product on the simplicial complex K:<sup>7</sup>

$$\langle \phi | \psi \rangle := \sum_{\sigma_p} V_{\sigma_p}^{(d)} \phi_{\sigma_p} \psi_{\star \sigma_p}^* = \langle \phi | \sum_{\sigma_p} V_{\sigma_p}^{(d)} | \sigma_p \rangle \langle \star \sigma_p | \psi \rangle , \qquad (2.22)$$

where we took a position-space measure into account in terms of the *d*-volumes  $V_{\sigma_p}^{(d)}$  associated with the pairs of primal and dual *p*-simplices. This inner product is obtained by a resolution of the identity

$$\sum_{\sigma_p} V_{\sigma_p}^{(d)} |\sigma_p\rangle \langle \star \sigma_p | = \mathbb{1} , \qquad (2.23)$$

which for reasons of consistency demands a modification of the pairing of primal and dual chains:

$$\langle \star \sigma_p | \sigma_p' \rangle := \frac{1}{V_{\sigma_p}^{(d)}} \delta_{\sigma\sigma'} \,. \tag{2.24}$$

By the third duality between chains and cochains, this directly yields the same form of completeness and orthonormality relations for primal and dual cochains. While the *p*-volumes in (2.10) and (2.16) are not needed to define the field space, the position measure  $V_{\sigma_p}^{(d)}$  is crucial and it is at this stage where the geometric interpretation is needed.

For the inner product to be well-defined, the space of p-form fields does not have to be constrained further. Since its dimension is the number of p-simplices in the finite complex K,

$$\dim \Omega^p(K) = \dim \Omega^{d-p}(\star K) = \operatorname{Card}(K_p) < \infty, \qquad (2.25)$$

the field space  $\Omega^p(K) \cong \Omega^{d-p}(\star K)$  is already the discrete  $L^2$  space.

## 2.7 The bra-ket formalism

To define a formalism with unique types of bras and kets, we now go one step further (beyond [36]) and identify primal chains with dual cochains and dual chains with primal cochains:

$$|\sigma_p\rangle \equiv |\star \sigma_p\rangle, \qquad \langle \sigma_p| \equiv \langle \star \sigma_p|.$$
 (2.26)

symmetric difference instead of the union [36] of simplices in the subdivision has to be used. This can also happen in the case of primal Delaunay triangulations.

<sup>&</sup>lt;sup>7</sup>Again analogous to [36] but different in details of convention.

We end up having just one complete orthonormal basis,

$$\left\langle \sigma_p | \sigma'_p \right\rangle = \frac{1}{V_{\sigma_p}^{(d)}} \delta_{\sigma\sigma'} \,, \tag{2.27}$$

$$\sum_{\sigma_p} V_{\sigma_p}^{(d)} |\sigma_p\rangle \langle \sigma_p| = \mathbb{1}.$$
(2.28)

With this identification, we can now write the Hodge dual (2.16) as

$$\langle *\phi | \sigma_p \rangle := \langle \star\sigma_p | \phi \rangle = \langle \sigma_p | \phi \rangle = \langle \phi | \sigma_p \rangle^* \,. \tag{2.29}$$

One still has to be careful with the sign when taking the dual twice, as

$$\langle * * \phi | \sigma_p \rangle = (-1)^{p(d-p)} \langle \phi | \sigma_p \rangle.$$
(2.30)

The following commutative diagram shows the identifications and dualities by which the discrete  $L^2$  position function space is defined:

All the maps are well known [36, 38] except for the last identification denoted as " $\equiv$ ", which makes it possible to have a Dirac position space notation for arbitrary *p*-fields on simplicial pseudo-manifolds with an assigned set of geometric data.

Note that, since by the last identification the pairing of the chain-cochain duality is modified, too, the fields finally have bra and ket component expansion

$$\langle \phi | = \sum_{\sigma_p \in K} V_{\sigma_p}^{(d)} \phi_{\sigma_p} \langle \sigma_p | \quad \longleftrightarrow \quad |\phi\rangle = \sum_{\sigma_p \in K} V_{\sigma_p}^{(d)} \phi_{\sigma_p}^* |\sigma_p\rangle .$$
(2.32)

## 3 Laplacian on simplicial pseudo-manifolds

In order to define the Laplacian, we have first to introduce discrete calculus on complexes by defining a differential. Then, the formal expression of the Hogde Laplacian is well defined on simplicial pseudo-manifolds and we can analyze its properties in the case of dual scalar fields.

## 3.1 Exterior calculus on complexes

The exterior differential operator on discrete forms is constructed by taking Stokes theorem as a definition [36, 38]. For the integration of the differential of a form  $\phi \in \Omega^{p-1}(K)$  over one simplex  $\sigma_p$  in the triangulation of a pseudo-manifold with corresponding complex K, the theorem states that

$$d\phi(\sigma_p) = \int_{\sigma_p} d\phi_{\text{cont}} = \int_{\partial \sigma_p} \phi_{\text{cont}} = \phi(\partial \sigma_p) \,. \tag{3.1}$$

Therefore, we define the differential of  $\phi \in \Omega^{p-1}(K)$  on an abstract simplicial complex K as<sup>8</sup>

$$d\phi(\sigma_p) = V_{\sigma_p} \langle d\phi | \sigma_p \rangle := \phi(\partial \sigma_p) := \sum_{\sigma_{p-1} \in \partial \sigma_p} \operatorname{sgn}(\sigma_{p-1}, \sigma_p) V_{\sigma_p} \langle \phi | \sigma_{p-1} \rangle .$$
(3.2)

<sup>&</sup>lt;sup>8</sup>The differential operator is just a modified version of the coboundary operator, which is the operator adjoined to the boundary operator with respect to the third duality between chains and cochains. It is modified because in the convention chosen here we have to explicitly keep track of the volume factors. In the math convention [36], on the other hand, the differential is exactly the coboundary operator.

The sign factor takes into account the orientation of the faces  $\sigma_{p-1} = (i_1 \dots \hat{i}_j \dots \hat{i}_p)$  relatively to the bulk simplex  $\sigma_p = (i_1 \dots i_p)$  via the permutation of their vertices,

$$\operatorname{sgn}(\sigma_{p-1}, \sigma_p) := \operatorname{sgn}(i_1 \dots \hat{i}_j \dots i_p) \operatorname{sgn}(i_1 \dots i_p).$$
(3.3)

Similarly, the differential on dual forms  $\phi \in \Omega^{d-p-1}(\star K) \cong \Omega^{p+1}(K)$  is defined as

$$V_{\hat{\sigma}_{d-p}}\left\langle\hat{\sigma}_{d-p}|\mathrm{d}\phi\right\rangle := \sum_{\hat{\sigma}_{d-(p+1)}\in\partial\hat{\sigma}_{d-p}} \operatorname{sgn}\left(\hat{\sigma}_{d-(p+1)},\hat{\sigma}_{d-p}\right) V_{\hat{\sigma}_{d-(p+1)}}\left\langle\hat{\sigma}_{d-(p+1)}|\phi\right\rangle , \qquad (3.4)$$

or equivalently

$$V_{\star\sigma_p} \langle \sigma_p | \mathrm{d}\phi \rangle := \sum_{\sigma_{p+1}; \sigma_p \in \partial\sigma_{p+1}} \operatorname{sgn}(\sigma_{p+1}, \sigma_p) V_{\star\sigma_{p+1}} \langle \sigma_{p+1} | \phi \rangle .$$
(3.5)

One can easily check that indeed the differential on the dual complex is the adjoint to the differential on the primal one,  $\langle d\phi | \psi \rangle = \langle \phi | d\psi \rangle$ . More precisely, if we do not write the inner product directly as a pairing of bra and ket but as a bilinear form on either  $\Omega^p(K)$  or  $\Omega^{d-p}(\star K)$ , the adjoint operator of the differential as usual is

$$\delta := (-1)^{d(p+1)+1} * d*, \qquad (3.6)$$

taking into account the sign of multiple Hodge operations [36].

## 3.2 Laplacian on dual scalar fields and its properties

Using the above notions of discrete differential and codifferential, we can now simply define the discrete Laplacian using the standard definition of the Hodge–Laplace–Beltrami operator in the well-known form [45]

$$\Delta_p := \Delta = \delta \mathbf{d} + \mathbf{d}\delta \,, \tag{3.7}$$

which has now a well-defined meaning on arbitrary *p*-forms on a simplicial pseudo-manifold. In particular, we are interested in the action of this Laplacian on dual scalar fields  $\phi \in \Omega^0(\star K) \cong \Omega^d(K)$ , that is, fields living on *d*-simplices:<sup>9</sup>

$$(-\Delta_{d}\phi)_{\hat{\sigma}_{0}} = -\left\langle \hat{\sigma}_{0} \middle| (-1)^{d(1+1)+1} * d * d\phi \right\rangle$$

$$= \left\langle d * d\phi \middle| \sigma_{d} \right\rangle$$

$$= \frac{1}{V_{\sigma_{d}}} \sum_{\sigma_{d-1} \in \partial \sigma_{d}} \operatorname{sgn}(\sigma_{d-1}, \sigma_{d}) V_{\sigma_{d-1}} \left\langle * d\phi \middle| \sigma_{d-1} \right\rangle$$

$$= \frac{1}{V_{\sigma_{d}}} \sum_{\sigma_{d-1} \in \partial \sigma_{d}} \operatorname{sgn}(\sigma_{d-1}, \sigma_{d}) V_{\sigma_{d-1}} \left\langle \hat{\sigma}_{1} \middle| d\phi \right\rangle$$

$$= \frac{1}{V_{\sigma_{d}}} \sum_{\sigma_{d-1} \in \partial \sigma_{d}} \operatorname{sgn}(\sigma_{d-1}, \sigma_{d}) \frac{V_{\sigma_{d-1}}}{V_{\hat{\sigma}_{1}}} \sum_{\hat{\sigma}_{0} \in \partial \hat{\sigma}_{1}} \operatorname{sgn}(\hat{\sigma}_{0}, \hat{\sigma}_{1}) \left\langle \hat{\sigma}_{0} \middle| \phi \right\rangle$$

$$= \frac{1}{V_{\sigma_{d}}} \sum_{\sigma_{d}' \sim \sigma_{d}} \frac{V_{\sigma_{d}} \cap \sigma_{d}'}{V_{\star}(\sigma_{d} \cap \sigma_{d}')} \left( \phi_{\hat{\sigma}_{0}} - \phi_{\hat{\sigma}_{0}'} \right) . \tag{3.8}$$

The dual volumes  $V_{\star(\sigma_d \cap \sigma'_d)}$  in the denominator are the lengths of the dual edges between dual points  $\hat{\sigma}_0$  and  $\hat{\sigma}'_0$ , and we write them as  $\hat{l}_{\sigma\sigma'} = V_{\star(\sigma \cap \sigma')}$  (suppressing from now on the dimension

<sup>&</sup>lt;sup>9</sup>In the literature of Regge calculus a Laplacian of the same form is derived for a primal scalar field (i.e., a scalar field living on the vertices of the primal simplicial complex) in the circumcentric case [8]. Then the dual Laplacian  $\Delta_d$  is guessed to have exactly the form eq. (3.8)

index in  $\sigma = \sigma_d$ ). Thus the action of the Laplacian on a scalar field ket

$$-\Delta_{d}|\phi\rangle = \sum_{\sigma} V_{\sigma}|\sigma\rangle \langle\sigma|\Delta_{d}\phi\rangle$$
  
$$= \sum_{\sigma} |\sigma\rangle \sum_{\sigma'\sim\sigma} \frac{V_{\sigma\cap\sigma'}}{\hat{l}_{\sigma\sigma'}} (\langle\sigma|\phi\rangle - \langle\sigma'|\phi\rangle)$$
  
$$= \left[\sum_{\sigma} \left(\sum_{\sigma'\sim\sigma} w_{\sigma\sigma'}\right) |\sigma\rangle \langle\sigma|\right] |\phi\rangle - \left(\sum_{\sigma} \sum_{\sigma'\sim\sigma} w_{\sigma\sigma'} |\sigma\rangle \langle\sigma'|\right) |\phi\rangle$$
  
$$=: D|\phi\rangle - A|\phi\rangle.$$
(3.9)

is of the general type of a graph Laplace matrix [52]: on the 1-skeleton graph of the dual complex it is a difference of an off-diagonal adjacency matrix A in terms of weights

$$w_{\sigma\sigma'} := \frac{V_{\sigma\cap\sigma'}}{\hat{l}_{\sigma\sigma'}} \tag{3.10}$$

and a diagonal degree matrix  ${\cal D}$  with entries

$$D_{\sigma\sigma} = \sum_{\sigma' \sim \sigma} w_{\sigma\sigma'}.$$
(3.11)

The Laplace matrix position elements  $(-\Delta_d \phi)_{\sigma}$ , on the other hand, come with an additional inverse volume and are

$$\frac{w_{\sigma\sigma'}}{V_{\sigma}}.$$
(3.12)

By definition, such discrete (graph) Laplacians obey three desirable properties [52, 53]:

- 1. Null condition:  $(\Delta_d \phi) = 0$  if, and only if,  $\phi$  is constant. This is obvious because  $\Delta_d \phi$  is the difference of position values of  $\phi$ . The zero mode of the spectrum of  $\Delta_d$  reflects the fact that K corresponds to a closed pseudo-manifold.
- 2. Self-adjointness: The Laplace operator is self-adjoint with respect to the inner product

$$\langle \phi | \Delta_d \psi \rangle = \langle \Delta_d \phi | \psi \rangle . \tag{3.13}$$

This is reflected by the symmetry of its weights  $w_{\sigma\sigma'}$ , though at the level of position coefficients  $(\Delta_d \phi)_{\sigma}$ , eq. (3.8), the inverse-volume factor  $V_{\sigma}^{-1}$  spoils this symmetry.

3. Locality: The action of  $\Delta_d$  at any given position,  $(\Delta_d \phi)_{\sigma}$ , is not affected by field values  $\phi_{\sigma'}$  at non-neighboring positions  $\sigma' \approx \sigma$ . In discrete calculus, this comes directly from the definition of the Laplacian as a second-order differential operator.

In the case of a simplicial decomposition |K| of a pseudo-manifold M, a further natural condition which is built into the formalism from the start (by the definition of differentials via Stokes theorem) is the

4. Convergence to the continuum Laplacian under refinement of triangulations.

To see this, consider a region  $\Omega \in M$  large compared to the scale  $a \sim (V_{\sigma_p})^{\frac{1}{p}}$  of simplices  $\sigma_p \in K$ , in which the function  $\phi$  and its derivatives do not vary strongly. Using eq. (2.21),  $V_{\sigma \cap \sigma'}V_{\star(\sigma \cap \sigma')} \approx d \cdot V_{\sigma \cap \sigma'}^{(d)}$ , we have

$$\sum_{\sigma \in \Omega} V_{\sigma}(-\Delta_{d}\phi)_{\sigma} = \sum_{\sigma \in \Omega \sigma' \sim \sigma} \frac{V_{\sigma \cap \sigma'}}{\hat{l}_{\sigma \sigma'}} \left(\phi_{\sigma} - \phi_{\sigma'}\right) \approx d \sum_{\sigma \in \Omega \sigma' \sim \sigma} V_{\sigma \cap \sigma'}^{(d)} \frac{\phi_{\sigma} - \phi_{\sigma'}}{\hat{l}_{\sigma \sigma'}^{2}}$$
$$\approx 2d \operatorname{Vol}(\Omega) \sum_{\hat{\sigma}_{1} \in \Omega} \frac{\phi_{\sigma} - \phi_{\sigma'}}{a^{2}}.$$
(3.14)

Summing over all the dual edges  $\hat{\sigma}_1 \in \Omega$  gives effectively a rotationally invariant expression. In particular, it is an average over hypercubic lattices and the difference term can readily be seen to be the Laplacian in the continuum limit, just as in standard lattice field theory with hypercubic lattice size a. As  $\phi_{\sigma+ae_{\mu}} \xrightarrow{\to} \phi_{\sigma} + a (\partial^{\mu}\phi)_{\sigma} e_{\mu} + \mathcal{O}(a^2)$ , the difference term gives

$$\sum_{\sigma'}^{2d} \frac{\phi_{\sigma} - \phi_{\sigma'}}{a^2} = -\sum_{\mu=1}^d \frac{1}{a} \left( \frac{\phi_{\sigma+ae_{\mu}} - \phi_{\sigma}}{a} - \frac{\phi_{\sigma} - \phi_{\sigma-ae_{\mu}}}{a} \right)$$
$$\xrightarrow[a \to 0]{} \sum_{\mu=1}^d \frac{(\partial_{\mu}\phi)_{\sigma} - (\partial_{\mu}\phi)_{\sigma-ae_{\mu}}}{a} e^{\mu} \approx -\sum_{\mu=1}^d (\partial^{\mu}\partial_{\mu}\phi)_{\sigma} . \tag{3.15}$$

Despite the validity of the above properties, one has to expect that it is not possible to preserve all the features of the continuum Laplacian in the discrete setting. This has been shown in the case of two-dimensional triangulations [53]. As a result, the definition of a discrete counterpart of the continuum Laplacian cannot be unique. In our case, it is therefore natural to wonder which properties of the continuum Laplacian are not preserved by the discrete Laplacian  $\Delta_d$ .

The answer turns out to depend also on the specific choice of the geometry of the dual complex, that is, on the choice of its geometric embedding into the primal complex. The two distinguishing features are linear precision and positivity.

5. Linear precision:  $(\Delta_d \phi)_{\sigma} = 0$  for straight-line triangulations |K| of flat space  $M \subset \mathbb{R}^d$  and linear functions  $\phi(x^{\mu}) = c + \sum_{i=1}^{d} c_{\mu} x^{\mu}$  in Cartesian coordinates  $x^{\mu}$ . By linearity, this is equivalent to a vanishing Laplacian  $(\Delta_d x)_{\sigma} = 0$  of the coordinate field x (considered as a bunch of scalars  $x^{\mu}$ ).

Linear precision holds for circumcentric dual geometries, in which case the dual lengths are  $\hat{l}_{\sigma\sigma'} = |x_{\hat{\sigma}} - x_{\hat{\sigma}'}|$  and (with unit face normals  $\hat{n}_{\sigma\sigma'} = \frac{x_{\hat{\sigma}} - x_{\hat{\sigma}'}}{|x_{\hat{\sigma}} - x_{\hat{\sigma}'}|}$ )

$$(\Delta_d x)_{\sigma} \sim \sum_{\sigma' \sim \sigma} \frac{V_{\sigma \cap \sigma'}}{\hat{l}_{\sigma \sigma'}} \left( x_{\hat{\sigma}} - x_{\hat{\sigma}'} \right) = \sum_{\sigma' \sim \sigma} V_{\sigma \cap \sigma'} \hat{n}_{\sigma \sigma'} = 0$$
(3.16)

is true because these are exactly the closure conditions for the polyhedron  $\sigma$ . This property fails, on the other hand, for the barycentric case. One could heuristically understand this by noting that generically  $\hat{l}_{\sigma\sigma'} \neq |x_{\hat{\sigma}} - x_{\hat{\sigma}'}|$  in any dimension for the barycentric dual edges, so that  $(\Delta_d x)_{\sigma}$ reduces to a sum over normals of a set of modified faces, which cannot be expected to close, in general.

The second property is

6. Positivity of the weights:  $w_{\sigma\sigma'} > 0$ . It is also called Markov property [54] and is directly related to Osterwalder–Schrader positivity. The latter is crucial for a Euclidean quantum field theory to yield unitarity in the corresponding Lorentzian theory after Wick rotation [55].

Positivity holds if all the volumes in the weights are positive. This is generically true for barycentric duals. For circumcentric duals the situation is less general. Positivity does hold for circumcentric duals of regular complexes (where the circumcenters lie in the simplices).

However, this is not the case for irregular circumcentric duals. When a circumcenter does not lie inside the simplex, the part of the dual length associated with this simplex is negative such that in some cases the sum of the two parts is negative (see fig. 2), inducing negative Laplace matrix weights.

Therefore we see that, as anticipated, the choice of geometry of the dual complex is crucial, yielding different properties for the discrete Laplacian. In quantum gravity, in particular in the

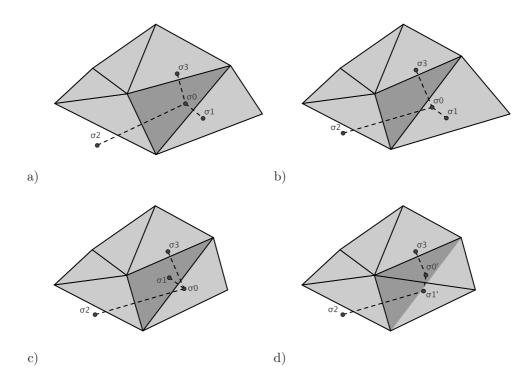


Figure 2. Examples of the dual edges to the the faces of a triangle in a simplicial d = 2 complex: In the first picture (a) the dual edges are the sum of the distance of the dual vertices  $\hat{\sigma}_i$  to the face. In the second (b) the dual vertex  $\hat{\sigma}_0$  lies outside the triangle. Its distance to the face line therefore has to be subtracted, but the dual length  $\hat{l}_{\hat{\sigma}_0\hat{\sigma}_1}$  is still positive. In the third case (c) both the vertices of  $\hat{l}_{\hat{\sigma}_0\hat{\sigma}_1}$  lie outside their simplices such that  $\hat{l}_{\hat{\sigma}_0\hat{\sigma}_1}$  is negative. Exactly when this happens the triangulation cannot be Delaunay because the circumcenter is closer to the neighbor than to its own triangle. The forth picture (d) shows the Delaunay triangulation for the primal points of (c), where the triangle originally considered, and thus its dual vertex, does not exist (though still shaded for comparison).

investigation of its possible fractal structure, the barycentric dual is to be preferred. Indeed, in this context, the null-condition, symmetry and positivity are generically required. They are even taken as the defining properties in fractal spectral theory [54] (see appendix A). On the contrary, it could be expected on general grounds that standard locality and linear precision might be violated. Though we do have locality for  $\Delta_d$  in our simplicial context the relation between such discrete and the continuum notion of locality is not immediate. Indications of a breakdown of standard locality actually exist in several approaches to quantum gravity (e.g., [56]). Also, in fractional calculus, which can be used as an effective description of fractal and other anomalous spacetimes, the Laplacian may be composed by fractional integro-differential operators, which are non-local (by the dependence on non-neighboring points) [33, 57–59].

Linear precision is not needed either, because we are not in flat space and its only relevance is as an asymptotic property in the continuum limit to flat spaces. But as we have argued, this is already fulfilled up to higher-order corrections. That this works despite the lack of linear precision can be easily understood by noting that the average difference between circumcentric and barycentric dual lengths is only of higher order in the scale of refined triangulations. Fractional spacetimes are a continuum example where this property is violated, in all self-adjoint Laplacians (also in the second-order one, due to the presence of a measure weight to the right of the derivatives) [33, 60].

## 4 Generalizations and applications

## 4.1 Generalizations of simplicial pseudo-manifolds

So far we have detailed the formalism for primal simplicial pseudo-manifolds equipped with a geometry. There are two possible generalizations which are important for applications: pseudo-manifolds with boundary and more general polyhedral complexes instead of simplicial ones. We sketch such generalizations without going into the details, as the construction is actually straightforward.

## Boundaries

An abstract simplicial pseudo d-manifold K is allowed to have a boundary  $\partial K$  when the nonbranching condition is relaxed. The (d-1)-simplices comprised in  $\partial K$  have to be faces of only one d-simplex each. Therefore the non-branching condition for simplicial pseudo-manifolds with boundary states that each (d-1)-simplex is face of one or two d-simplices. The other conditions of section 2.4 remain.

Then  $\partial K$ , or more precisely all the elements of  $(\partial K)_{d-1}$ , can be obtained from the action of the boundary operator  $\partial$  on the *d*-chain comprising all *d*-simplices:

$$\left|\partial K\right\rangle = \partial \sum_{\sigma_d \in K_d} \left|\sigma_d\right\rangle,\tag{4.1}$$

since the interior (d-1)-simplices cancel pairwise, because of orientation.

The boundary  $\partial K$  is just a (d-1)-subcomplex of K. Without the original non-branching condition holding, the construction of a dual  $\star \partial K$  is only possible using the simplicial subdivision explained above yielding half lines, or in general half cells dual to face simplices. These are distinguished as exterior cells  $\hat{\sigma}^e \in \star \partial K$  from the usual interior ones  $\hat{\sigma}^i = \hat{\sigma} \in \star K \setminus \star \partial K$ .

For the calculus of fields  $\phi \in \Omega^p(K)$ , p < d, on the simplicial pseudo-manifold nothing is changed beside exterior cells having volumes accordingly. Only for *d*-forms  $\phi \in \Omega^d(K)$  it is necessary to define their boundary values extending their domain from  $K_d$  to  $K_d \cup (\partial K)_{d-1}$ . In general, it is desirable to have a boundary field also for *d*-forms. One can then choose boundary conditions for such fields, for example Dirichlet ones  $\phi|_{\partial K} = *\phi|_{*\partial K} = 0$ .

### Cell complexes

Furthermore, one is interested in more general cell complex pseudo-manifolds on the primal side, too. This poses no issue as far as cell complexes are concerned allowing for some simplicial decomposition, for which one can use the formalism we have presented. Typically, one just wants to generalize from dual (d+1)-valent vertices to vertices of arbitrary valence, that is, from primal simplices to arbitrary polytopes. At the level of geometric realizations, the possibility of decompositions and hence the relation to simplicial pseudo-manifolds is obvious. One has only to take care of generalizing the definition appropriately at the abstract combinatorial level. Therefore, along the lines of [38] we sketch how the formalism is easily generalized to cell complexes obeying the three pseudo-manifold conditions of section 2.4 at the topological level.

A primal *p*-cell  $\sigma_p$  now is a set of points homeomorphic to a closed unit *p*-ball  $B_p$ ; its boundary  $\partial \sigma_p$  is the part of  $\sigma_p$  homeomorphic to the boundary to  $\partial B_p$ . It can be represented by the ordered set of vertices of a *p*-polytope. A cell *d*-complex *K* is a collection of *p*-cells,  $p = 0, 1, \ldots, d$ , with the following two properties:

- The boundary  $\partial \sigma_p$  of each *p*-cell  $\sigma_p \in K$  is the union of some (p-1)-cells  $\sigma_{p-1} \in K$ .
- The intersection of any two *p*-cells is empty or an element of the boundary of both.

As before, an orientation is given by the representation in terms of ordered sets.

If K is non-branching, strongly connected and dimensional homogeneous it has a dual complex  $\star K$  with cellular structure induced by the adjacency relations of K, just as in the simplicial case. Then, the whole formalism of discrete exterior calculus works through with an appropriate definition of relative signs  $\operatorname{sgn}(\sigma_{p-1}, \sigma_p)$ . All the formal definitions are already general enough to account for this generalization.

## 4.2 Applications: momentum transform and heat kernel

#### Momentum transform

Let us assume that the finite simplicial complex K has a geometric interpretation in terms of a set of finite, non-degenerate primal and dual volumes. In particular, for the case of the Laplacian acting on a scalar function the *d*-volumes  $V_{\sigma_d}$  and dual edge lengths  $V_{\hat{\sigma}_1}$  should be non-vanishing. Then the computation of eigenvalues  $\lambda$  and eigenfunctions  $|\lambda\rangle$  of the Laplacian reduces to a purely linear algebraic issue. It depends on the combinatorics of the simplicial complex as well as on the geometric data. Note that in the defining equation

$$\left(-\Delta_d e^{\lambda}\right)_{\sigma} := -\left\langle\sigma|\Delta_d|\lambda\right\rangle = \lambda\left\langle\sigma|\lambda\right\rangle =: \lambda e^{\lambda}_{\sigma} \tag{4.2}$$

indeed the asymmetric matrix elements  $w_{\sigma\sigma'}/V_{\sigma}$  are essential. The eigenvalues  $\lambda$  are defined with a relative minus sign such that they are positive on, for example, closed pseudo-manifolds [52].

If the matrix elements of the Laplacian are finite and well defined in the complex field, that is, if  $\Delta$  is just a linear map in a finite vector space, then the Laplacian is diagonalizable and the eigenspaces of its eigenvectors comprise the vector space. Assuming this, the eigenfunctions  $e_{\sigma}^{\lambda}$ of the Laplacian (where the label  $\lambda$  is meant to run not only over eigenvalues but also over their multiplicities) form a complete orthonormal basis defining momentum space. The measure  $V_{\lambda}$  of this space is thus defined as the norm chosen for the orthogonal eigenspace basis elements  $|\lambda\rangle$  such that orthonormality,

$$\langle \lambda | \lambda' \rangle = \sum_{\sigma} V_{\sigma}^{(d)} e_{\sigma}^{\lambda} e_{\sigma}^{\lambda'*} = \frac{1}{V_{\lambda}} \delta_{\lambda\lambda'} , \qquad (4.3)$$

and consistently completeness,

$$\sum_{\lambda} V_{\lambda} |\lambda\rangle \langle \lambda| = \mathbb{1}, \qquad (4.4)$$

hold.

For a momentum measure of the usual dimension  $[V_{\lambda}] = d$  one could for example normalize the coefficients  $e_{\sigma}^{\lambda}$  with respect to the standard Euclidean measure. Although this choice of dimension is not necessary, since any physical quantity will be automatically normalized by the measure factors  $V_{\lambda}$ , it is the usual convention in continuum physics to have position and momentum space measure of inverse dimension. In this case, momentum transform is an automorphism (see [33, 60] for further discussion). Transformations of fields  $\phi$  from position to momentum space and back are straightforwardly given by the resolution of the identity in either position or momentum space:

$$\phi^{\lambda} = \langle \phi | \sum_{\sigma_p} V_{\sigma_p}^{(d)} | \sigma_p \rangle \langle \sigma_p | \lambda \rangle = \sum_{\sigma_p} V_{\sigma_p}^{(d)} e_{\sigma}^{\lambda *} \phi_{\sigma} , \qquad (4.5)$$

$$\phi_{\sigma} = \langle \phi | \sum_{\lambda} V_{\lambda} | \lambda \rangle \langle \lambda | \sigma \rangle = \sum_{\lambda} V_{\lambda} e_{\sigma}^{\lambda} \phi^{\lambda} .$$
(4.6)

#### Heat kernel

With a transform between position and momentum space at hand, one can easily deal also with functions of the Laplacian. We illustrate this with the example of the heat kernel, the solution to the heat equation on K in terms of a continuous diffusion parameter  $\tau$ .

The formal expression of the heat kernel  $e^{\tau \Delta_d}$  now has a well-defined meaning on a simplicial pseudo-manifold K for functions on the dual complex:

$$K_{\sigma\sigma'}(\tau) := \left\langle \sigma' | e^{\tau \Delta_d} | \sigma \right\rangle = \left\langle \sigma' | e^{-\lambda \tau} \sum_{\lambda} V_\lambda | \lambda \right\rangle \left\langle \lambda | \sigma \right\rangle = \sum_{\lambda} V_\lambda e^{-\lambda \tau} e_{\sigma'}^{\lambda *} e_{\sigma}^{\lambda}.$$
(4.7)

We can use the heat kernel to calculate the diffusion of some initial matter distribution  $\rho$  parametrized by  $\tau$  to be

$$\rho_{\sigma}(\tau) := \langle \rho | K(\tau) | \sigma \rangle = \langle \rho | e^{\tau \Delta_d} | \sigma \rangle = \langle \rho | \sum_{\sigma'} V_{\sigma'} | \sigma' \rangle \langle \sigma' | e^{\tau \Delta_d} | \sigma \rangle = \sum_{\sigma'} V_{\sigma'} K_{\sigma \sigma'}(\tau) \langle \rho | \sigma' \rangle$$

$$= \sum_{\sigma'} V_{\sigma'} K_{\sigma \sigma'}(\tau) \rho_{\sigma'} . \tag{4.8}$$

In particular, the heat kernel itself is the evolution  $\rho_{\sigma}(\tau) = K_{\sigma\sigma'}(\tau)$  for an initial distribution  $\rho_{\sigma} = \frac{1}{V_{\sigma}}\delta_{\sigma\sigma'}$  concentrated on one simplex  $\sigma'$ . In the continuum, this initial condition would correspond to a diffusing test particle.

The trace of the heat kernel, which gives the return probablity in diffusion processes, becomes

$$\mathcal{P}(\tau) := \operatorname{Tr} K_{\sigma\sigma'}(\tau) = \frac{1}{V} \sum_{\sigma} V_{\sigma} \sum_{\lambda} V_{\lambda} e^{-\tau\lambda} e_{\sigma}^{\lambda*} e_{\sigma}^{\lambda} = \frac{1}{V} \sum_{\lambda} V_{\lambda} e^{-\tau\lambda} \sum_{\sigma} V_{\sigma} e_{\sigma}^{\lambda*} e_{\sigma}^{\lambda}$$
$$= \frac{1}{V} \sum_{\lambda} e^{-\tau\lambda}.$$
(4.9)

While the spectrum of the Laplacian gives a closed expression for  $\mathcal{P}(\tau)$  in many cases, for numerical computations of combinatorially very large complexes it can alternatively be treated as a random walk. In this case, local probabilities are given for jumping from one simplex  $\sigma$  to a neighbor  $\sigma'$  given by the matrix elements  $w_{\sigma\sigma'}/V_{\sigma}$  of the Laplacian. This is the technique used in dynamical triangulations [20, 27], which will be discussed below, and random combs and multi-graphs [61–64].

## 5 Classical expressions of the Laplacian

The general form of the discrete Laplacian depends both on the combinatorial structure of the underlying simplicial complex and on its discrete geometry through the various volume factors.  $\Delta$  takes then different concrete expressions, depending on the variables used to encode the geometry of the simplicial complex. These expressions would be needed for explicit calculations in different formulations of classical discrete gravity and, successively, in applications to quantum gravity models. In the following, we provide some examples for the discrete Laplacian constructed in the geometric variables used in various approaches to classical and quantum gravity.

#### 5.1 Regge edge length variables

The most common variables to describe the geometry of a simplicial pseudo-manifold are the edge lengths  $\{l_{ij}\}$ . In the standard version of Regge calculus [65, 66], these are taken as configuration space for the geometries of piecewise flat triangulations.

The expressions for primal volumes are well known in the Regge literature, so the only geometric data needed for defining the dual scalar Laplacian  $\Delta_d$  are the dual edge lengths  $\hat{l}_{\sigma\sigma'}$ . We subdivide the dual edges into two parts  $\hat{l}^{\sigma}$  and  $\hat{l}^{\sigma'}$ , associated respectively with the simplex  $\sigma$  and  $\sigma'$ , so that  $\hat{l}_{\sigma\sigma'} = \hat{l}^{\sigma} + \hat{l}^{\sigma'}$ . These dual edge lengths depend on the chosen embedding of dual complex into the primal one.

In the barycentric case, when  $\hat{l}_{\hat{i}}^{\sigma}$  is the length of the edge dual to the face  $\sigma_{d-1} = (012...\hat{i}...d)$  contained inside the simplex  $\sigma_d = (012...d)$ , it is given by (see appendix B)

$$\hat{l}_{\hat{i}}^{\sigma} = \frac{1}{d(d+1)} \sqrt{d\sum_{j} l_{ij}^2 - \sum_{(jk)} l_{jk}^2} \,.$$
(5.1)

Then the matrix elements of the Laplacian (eq. (3.12)) for  $\sigma \cap \sigma' = (012...d) \cap (0'12...d) = (12...d)$  have the form

$$\frac{w_{\sigma\sigma'}}{V_{\sigma}} = d\left(d+1\right) \frac{1}{V_{012...d}} \frac{V_{12...d}}{\hat{l}_{\hat{0}}^{\sigma} + \hat{l}_{\hat{0}'}^{\sigma'}}.$$
(5.2)

These are well defined on simplicial geometries satisfying the strong generalized triangular inequalities, that is,  $V_{\sigma_p} > 0$  for all  $0 . In particular, these conditions ensure that the dual lengths <math>\hat{l}_i^{\sigma}$  are non-zero and positive.

This is not the case for the circumcentric dual where each  $\hat{l}^{\sigma}_{\hat{0}} \in \mathbb{R}$  can be negative or vanishing, and thus it is possible to have  $\hat{l}^{\sigma}_{\hat{0}} + \hat{l}^{\sigma'}_{\hat{0}'} = 0$ . This pole in the expression for the Laplacian, moreover, cannot be absorbed into the volumes as they depend only on the edges of  $\sigma$  but not of  $\sigma'$ . On the other hand, except for these singularities, the circumcentric Laplacian might be well defined even on degenerate geometries with  $V_{\sigma_d} = 0$ . This is true, for example, for d = 2, 3 where explicit expressions of the circumradius are known. In d = 2,

$$\frac{w_{(ijk)(jkl)}}{A_{ijk}} = \frac{8}{\pm \left(l_{ij}^2 + l_{ik}^2 - l_{jk}^2\right) \pm \frac{A_{ijk}}{A_{jkl}} \left(l_{jl}^2 + l_{kl}^2 - l_{jk}^2\right)},$$
(5.3)

and in d = 3

$$\frac{w_{(ijkl)(ijkm)}}{V_{ijkl}} = \frac{12A_{ijk}^2}{\pm\sqrt{(2A_{ijk}\mathcal{A}_{ijkl})^2 - (3l_{ij}l_{jk}l_{ki}V_{ijkl})^2} \pm \frac{V_{ijkl}}{V_{ijkm}}\sqrt{(2A_{ijk}\mathcal{A}_{ijkm})^2 - (3l_{ij}l_{jk}l_{ki}V_{ijkm})^2}}.$$
(5.4)

The sign of each dual length part  $\hat{l}^{\sigma}$  is positive if the circumcenter lies inside the *d*-simplex  $\sigma$  and negative if outside. With these descriptions of the Laplacian at hand, one can compare with other discrete Laplacians in the literature.

#### Sorkin's discrete Laplacian

In [67] a formalism with special "barycentric" coordinates (not to be confused with the mathematical notion, where unit vectors are attached to corners) is developed. As done also in [68], it can be expressed in terms of the dihedral angles as a "cotangens" Laplacian (with inverse volume factor) for primal scalar fields. In d = 2, with  $\alpha_{ij}^{\sigma_2}$  the angle opposite to the edge (ij) in the triangle  $\sigma_2$ , it is given by

$$-(\Delta_0 \phi)_i = \frac{1}{V_{\star(i)}} \sum_j \left( \sum_{\sigma_2 \ni (ij)} \cot \alpha_{ij}^{\sigma_2} \right) (\phi_i - \phi_j), \qquad (5.5)$$

and it is easy to show its equivalence to the Laplacian coming from discrete calculus with circumcentric duals.<sup>10</sup> In d = 3,

$$-(\Delta_0 \phi)_i = \frac{1}{V_{\star(i)}} \sum_j \left( \sum_{\sigma_3 \ni (ij)} l_{\hat{i}\hat{j}}^{\sigma_3} \cot \alpha_{ij}^{\sigma_3} \right) (\phi_i - \phi_j), \qquad (5.6)$$

<sup>10</sup>Elementary geometric arguments yield  $\hat{l}_{\hat{i}}^{(ijk)} = \sqrt{R^2 - (l_{jk}/2)^2} = (l_{jk}/2) \cot \alpha_{ij}^{\sigma_2}$ .

where the opposite dihedral angle  $\alpha_{ij}^{\sigma_2}$  now is between faces sharing the opposite edge  $l_{\hat{i}\hat{j}}^{\sigma_3}$  in the tetrahedron  $\sigma_3$ .<sup>11</sup> From the equivalence in d = 2 it is tempting to conjecture equivalence also for  $d \geq 3$ , but this remains to be proven.

#### Laplacian in dynamical triangulations

A different way of encoding the simplicial geometry of a piecewise flat triangulation, still based on the Regge calculus description, is to fix all edge lengths to some constant value, and allow only changes in the combinatorics of the simplicial complex itself. This idea underlies the quantum gravity program of dynamical triangulations [66, 69]. For such equilateral configurations, the Laplacian coming from discrete calculus drastically simplifies (up to an overall factor) to a purely combinatorial graph Laplacian [52] of the form (3.9),

$$\Delta_d \propto D - A \,, \tag{5.7}$$

where the weights here are  $w_{\sigma\sigma'} = 1$  if  $\sigma$  and  $\sigma'$  are adjacent.

While in the Lorentzian version, named causal dynamical triangulations, this should be modified by introducing negative length squares for timelike edges, this modification is not performed since the theory is Wick rotated to Euclidean signature and actual calculations are performed in a reduced ensemble of Euclidean triangulations (those that can indeed be obtained by Wick rotating Lorentzian ones) [69].

## 5.2 First-order Regge calculus with (d-1)-face variables

An alternative version to edge-length Regge calculus is in terms of the (d-1)-face normals  $\omega^{\sigma_{d-1}}(\alpha)$ (expressed in the reference frame of the *d*-simplex  $\sigma^{\alpha}$ ) and Lorentz rotations (parallel transports)  $U(\alpha, \alpha')$  from frame to frame across neighboring simplices. In turn, the latter define holonomies (around closed plaquettes)  $W_{\alpha}(h) = U_{\alpha,\alpha+1}U_{\alpha+1,\alpha+2}\dots U_{\alpha-1,\alpha}$ , which are rotations in the plane orthogonal to hinges  $h \in K_{d-2}$  [70–72] and measure the local curvature. The class angles corresponding to the holonomies are therefore the deficit angles  $\theta_h = 2\pi - \sum_{\alpha} \theta_h^{\alpha}$ , as could be obtained from the dihedral angles  $\theta_h^{\alpha}$  at the hinge h in each d-simplex  $\sigma^{\alpha}$  sharing it (see also [8]).

We show how all geometric data needed for the Laplacian  $\Delta_d$  have an expression in terms of the face normals  $\omega^{\sigma_{d-1}}(\alpha)$ . While the (d-1)-volumes are just the modulus of the face normals themselves,

$$V_{\sigma_{d-1}} = |\omega^{\sigma_{d-1}}(\alpha)| , \qquad (5.8)$$

the *d*-volumes of simplices  $\sigma^{\alpha}$  can also be expressed by *d* of the face normals  $\omega^{i}(\alpha) = \omega^{\sigma_{d-1} = (012...\hat{i}...d)}$ as [70]

$$V_{\alpha} \equiv V_{\sigma^{\alpha}} = \left[\frac{1}{d!}\epsilon^{I_1\dots I_d}\epsilon_{i_1\dots i_d j}\omega^{i_1}_{I_1}(\alpha)\dots\omega^{i_d}_{I_d}(\alpha)\right]^{\frac{1}{d-1}},$$
(5.9)

where capital indices I, J, ... are in internal space. By the closure relations, it does not matter which face  $(012...\hat{j}...d)$  is left out if  $\sigma^{\alpha}$  is closed. Alternatively, one could also average over the choices of reference face.

An explicit expression of dual lengths can only be obtained using position coordinates on  $\sigma^{\alpha}$  as functions of the face normals. Barycentric coordinates  $z(\alpha)$ , that is coordinates for which the sum over vertices satisfies  $\sum_{i=1}^{d+1} z_i^I(\alpha) = 0$ , can be derived inverting the expression of the face normals in terms of discrete vielbeins (see eq. (B.1)) in these coordinates [70],

$$\omega_I^i(\alpha) = \frac{1}{(d-1)!^2} \sum_{k \neq i} \epsilon_{J_1 \dots J_{d-1}I} \epsilon^{i, i_1 \dots i_{d-1}, k} z_{i_1}^{J_1}(\alpha) \dots z_{i_{d-1}}^{J_{d-1}}(\alpha) , \qquad (5.10)$$

<sup>&</sup>lt;sup>11</sup>From private communication with Sebastian Steinhaus.

leading to

$$z_i^I(\alpha) = \frac{1}{(d-1)!} \frac{1}{(V_\alpha)^{d-2}} \sum_{k \neq i} \epsilon^{J_1 \dots J_{d-1}I} \epsilon_{i,i_1 \dots i_{d-1},k} \omega_{J_1}^{i_1}(\alpha) \dots \omega_{J_{d-1}}^{i_{d-1}}(\alpha) \,. \tag{5.11}$$

The barycentric dual length is particularly simple in these coordinates. It is just the distance from the barycenter of the tetrahedron with coordinate  $z^{I} = 0$  to the barycenter of a face

$$\hat{l}_{\hat{i}}^{\sigma} = \left| \sum_{j \neq i} z_j[\omega^i(\sigma)] \right| \,. \tag{5.12}$$

For the circumcentric case no such simplification can be expected. Still primal edge lengths can be expressed in the coordinates  $z(\alpha)$ , taking then advantage of the above expressions (eqs. (5.2), (5.3) and (5.4)).

As an example, we can give the (further simplified) expressions in d = 3. On  $\sigma^{\alpha} = (ijkl)$  (suppressing the frame label  $\alpha$ ),

$$z_i^I = \frac{1}{2} \frac{1}{V_\alpha} \sum_{r \neq i} \epsilon^{IJK} \epsilon_{imnr} \omega_J^m \omega_K^n = \frac{1}{2} \frac{1}{V_\alpha} \left( \omega^j \times \omega^k + \omega^k \times \omega^l + \omega^j \times \omega^l \right)^I , \qquad (5.13)$$

and the tetrahedron volume in terms of three of its face triangles is

$$(V_{\alpha})^2 = \frac{1}{6} \epsilon^{IJK} \epsilon_{ijkl} \omega_I^i \omega_J^j \omega_K^k \,. \tag{5.14}$$

Therefore, the dual length is

$$\hat{l}_{i}^{\alpha} = \frac{1}{3} |z_{j} + z_{k} + z_{l}| = \frac{1}{6V_{\alpha}} |\omega^{j} \times \omega^{k} + \omega^{k} \times \omega^{l} + \omega^{l} \times \omega^{j}|$$
$$= \frac{1}{6V_{\alpha}} \sqrt{\sum_{(mn)\in(jkl)} [\omega_{m}^{2}\omega_{n}^{2} - (\omega_{m} \cdot \omega_{n})^{2} + (\omega_{m} \cdot \omega_{r})(\omega_{r} \cdot \omega_{n}) - (\omega_{m} \cdot \omega_{n})\omega_{r}^{2}]}.$$

Using the closure condition  $\sum \omega^i = 0$ , this further simplifies to

$$\hat{l}_{i}^{\alpha} = \frac{1}{2V_{\alpha}} \left| \omega^{j} \times \omega^{k} \right| = \sqrt{\omega_{j}^{2} \omega_{k}^{2} - \left(\omega_{j} \cdot \omega_{k}\right)^{2}}$$
(5.15)

for some faces j, k. The matrix elements (3.12) of the Laplacian  $\Delta_d$  can then easily be computed combining all the above expressions.

Finally, we note that the volume form  $\omega^h(\alpha)$  of a hinge  $h = \sigma_{d-2}$  can be expressed in terms of two normals to two faces  $\sigma^{\alpha+1,\alpha}$ ,  $\sigma^{\alpha,\alpha+1}$  sharing it, in the frame of  $\sigma^{\alpha}$  [70]:

$$\omega_{IJ}^{h}(\alpha) = \frac{1}{V_{\alpha}} \omega_{[I}^{\alpha-1,\alpha}(\alpha) \omega_{J]}^{\alpha,\alpha+1}(\alpha) \,.$$
(5.16)

This gives a connection to flux variables, discussed in the next section, which are exactly these (d-2)-face normals.

## 5.3 Flux and area-angle variables

In d = 4, a useful alternative set of variables in simplicial geometry are the bivectors  $b_{ijk}^{IJ} = e_{ij}^{I} \wedge e_{ik}^{J}$ associated with triangles (ijk) (or their internal Hodge duals  $X_{ijk}^{IJ} = \epsilon_{KL}^{IJ} b_{ijk}^{KL}$ ), known as fluxes, and playing a prominent role in both canonical loop quantum gravity and spin-foam models [1, 73, 74]. In a geometric 4-simplex (ijklm), the triangle areas are

$$A_{ijk} = |X_{ijk}|, \qquad (5.17)$$

and volumes of tetrahedra can be computed using three of the fluxes associated with the four triangles on their boundary [75], regarding the bivectors as linear maps:

$$V_{ijkl}^2 = \frac{8}{9} \text{Tr} \left( *X_{ijk} \left[ *X_{jkl}, *X_{kli} \right] \right) \,. \tag{5.18}$$

Volumes of 4-simplices can be taken from the wedge product of two fluxes not lying in the same 3-hyperplane (thus not belonging to the same tetrahedron),

$$V_{ijklm} = |X_{ijk} \wedge X_{ilm}|.$$
(5.19)

Primal edge lengths can be expressed using the generalized sine formula as

$$l_{ij}^{2} = 2 \frac{|X_{ijk}|^{2} |X_{ijl}|^{2} - (X_{ijk} \cdot X_{ijl})^{2}}{\operatorname{Tr}\left(*X_{ijk}\left[*X_{jkl}, *X_{kli}\right]\right)}.$$
(5.20)

This gives all the buildings blocks for explicit expressions (eqs. (5.2), (5.3) and (5.4)) of the barycentric and circumcentric discrete Laplacian  $\Delta_d$  with elements (3.12).

In the spin representation in d = 3 + 1 LQG and d = 4 spin-foams (adapted to a simplicial context), the easiest variables to use are triangle areas and 3-volumes of tetrahedra. However, it is known that they form an overcomplete set of data to specify a four-dimensional simplicial geometry, and should be supplemented by additional constraints whose explicit form is not known [76, 77]. A more natural choice is to use areas  $A_{ijk}$  and dihedral angles  $\phi_{k,l}^{ij}$  between faces (ijk) and (ijl) hinged at the common edge (ij) [78]. This set of data encodes the same information as the fluxes  $X_{ijk}$ . In these variables, the relevant geometric data to compute the discrete Laplacian have the following expressions. The 3-volumes are

$$V_{ijkl}^{2} = \frac{A_{ijk}}{9} \sqrt{\sum_{j} A_{ijl}^{2} \sin^{2} \phi_{k,l}^{ij} A_{jkl}^{2} \sin^{2} \phi_{i,l}^{jk} - \sum_{(ij)} A_{ijl}^{4} \sin^{4} \phi_{k,l}^{ij}}, \qquad (5.21)$$

from which the 4-volumes are obtained via the generalized sine law<sup>12</sup>

$$V_{ijklm} = \frac{3}{4} \frac{1}{A_{ijk}} V_{ijkl} V_{ijkm} \sin \theta_{l,m}^{ijk} [\phi] , \qquad (5.22)$$

as well as the primal edge lengths

$$l_{ij} = \frac{2}{3} \frac{1}{V_{ijkl}} A_{ijk} A_{ijl} \sin \phi_{k,l}^{ij} \,. \tag{5.23}$$

Again, this is all the information needed to build the Laplacian  $\Delta_d$ .

## 6 Laplacian in models of quantum geometry

With the classical expressions of the dual scalar Laplacian  $\Delta_d$  in the appropriate geometric variables at hand, one can take one's favorite model of quantum gravity and promote  $\Delta_d$  to a quantum observable. For instance, one can either take  $\Delta_d$  as an operator acting on quantum states of spatial geometries in a canonical theory (e.g., in a LQG context) or as a classical function to be path integrated over with the quantum measure of a covariant theory (within a spin-foam or simplicial

$$\cos\theta_{l,m}^{ijk} = \frac{\cos\phi_{k,l}^{ij} - \sin\phi_{l,m}^{ij}\sin\phi_{m,k}^{ij}}{\cos\phi_{l,m}^{ij}\cos\phi_{m,k}^{ij}}$$

<sup>&</sup>lt;sup>12</sup>The angles  $\theta_{l,m}^{ijk}$  between 3-simplices (ijkl) and (ijkm) are functions of the area dihedral angles according to [78]

path integral setting). We now discuss briefly how such calculations could be set up, leaving explicit computations for future study.

In both types of approaches the main challenge beyond a purely formal quantization is to deal with possible singularities of the matrix entries of the Laplacian, coming from the inverse *d*-volumes in the barycentric case and from the inverse dual length part in the circumcentric case. In a canonical setting, these singularities may prevent the definition of the Laplacian operator as a bounded operator; in the covariant setting, they may produce divergences in explicit evaluations. Obviously, whether or not such difficulties arise depend on the details of the quantum theory considered, and depending on the precise structure of the Hilbert space of states or the path integral measure, as well as on the exact classical expression to be quantized, they may not necessarily pose a problem.

Furthermore, for many purposes, it is not the Laplacian  $\Delta_d$  as such but functions of it,  $f[\Delta_d]$ , which are of interest. These need not have the same quantization issues (e.g., possible singularities) as the Laplacian itself.

A good example is the trace of the heat kernel  $\mathcal{P}(\tau)$ , discussed in the classical simplicial setting above (section 4.2). Since it is of the general form  $\mathcal{P}(\tau) \sim e^{\tau \Delta}$ , one would expect that it vanishes exactly in those cases where the Laplacian is singular (see the example in appendix C). Thus one may even envisage cases in which observables functions of the Laplacian  $f[\Delta_d]$ , inserted within quantum geometric evaluations (e.g., path integrals), might even help to suppress pathological configurations corresponding to degenerate or divergent geometries.

In the context of a quantum theory of pure geometry without any dynamical matter, there are reasons to believe that quite in general only global functions of the Laplacian are suitable complete observables (beyond the kinematical level) since they are invariant under diffeomorphisms. The heat trace is a good example of an observable meeting these conditions.

## 6.1 Laplacian in canonical formalism

The best developed canonical approach to quantum gravity is LQG [1, 2]. The kinematical Hilbert space of states of spatial geometry is defined as a projective limit of Hilbert spaces  $\mathcal{H}_{\Gamma}$  of states associated with graphs  $\Gamma$ . Under certain assumptions [51], they can be considered as the 1-skeleton  $\Gamma = (\star K)_1$  of the dual of a combinatorial pseudo-manifold K. Since the valency of the nodes in  $\Gamma$ is left arbitrary in LQG, the complex has to be polyhedral in general, though often one restricts to the lowest non-trivial (non-vanishing volume) valency of d + 1, corresponding to primal simplicial pseudo-manifolds.<sup>13</sup>

The LQG states are cylindrical functions  $\psi_{\Gamma}(h_{\hat{\sigma}_1})$  of holonomies of the gauge group G = SU(2)on the links  $\hat{\sigma}_1$  of the graphs  $\Gamma$ . These variables encode the extrinsic geometry of the spatial slice. The same states can be transformed into functions of representations  $j_{\hat{\sigma}_1}$  on the links and intertwiners  $i_{\hat{\sigma}_0}$  between them on the nodes  $\hat{\sigma}_0$ , called spin network states  $\psi_{\Gamma}(j_{\hat{\sigma}_1}, i_{\hat{\sigma}_0})$ . A further possibility is to transform into a basis of fluxes  $X_{\hat{\sigma}_1}$  on the links, valued in the Lie algebra of the group [73]. These sets of dual variables encode the intrinsic geometry of the spatial slice.

The spin network states are the eigenstates of a commuting set of local geometric observables. In d = 2 + 1 these are the primal edge length operators  $\widehat{l_{\sigma_1}}$  dual to graph links  $\hat{\sigma}_1 = \star \sigma_1$ , with squared spectrum proportional to the Casimir of the group  $G = SO(3) \cong SU(2)$ :

$$\hat{l}_{\sigma_1}^2 \psi_{\Gamma}(j_{\hat{\sigma}_1}, i_{\hat{\sigma}_0}) \sim [j_{\star \sigma_1}(j_{\star \sigma_1} + 1) + c] \psi_{\Gamma}(j_{\hat{\sigma}_1}, i_{\hat{\sigma}_0}), \qquad (6.1)$$

<sup>&</sup>lt;sup>13</sup>In principle, one can take an expression of the Laplacian obtained from the geometric interpretation in a pseudomanifold setting and apply it even to graphs  $\Gamma$  which are not in the skeleton of the dual to a pseudo-manifold, as long as all the variables are defined.

with c = const being a quantization ambiguity.

In d = 3 + 1 the same holds with the difference that it is now primal triangles (more generally, polygons) to be dual to the graph links  $\hat{\sigma}_1 = \star \sigma_2$ , and the spins are then their areas  $\widehat{A_{\hat{\sigma}_2}}$  for which

$$\widehat{A}_{\sigma_2}^2 \psi_{\Gamma}(j_{\hat{\sigma}_1}, i_{\hat{\sigma}_0}) \sim [j_{\star \sigma_2}(j_{\star \sigma_2} + 1) + c] \psi_{\Gamma}(j_{\hat{\sigma}_1}, i_{\hat{\sigma}_0}).$$
(6.2)

The 3-volume operator  $\widehat{V_{\sigma_3}}$  for the tetrahedron (more generally, 3-cell) dual to a graph vertex has a (more complicated) spectrum in terms of the intertwiners  $i_{\star\sigma_3}$  [2].

Concerning length operators  $\hat{l}_{\sigma_1}$  for primal edges, there are several definitions available in the literature. In one such definition [79], eigenstates of  $\hat{l}_{\sigma_1}$  are linear combinations of the intertwiners, and the operators  $\hat{l}_{\sigma_1}$  corresponding to edges of the primal 3-cell, neither commute with the volume operator of the same 3-cell  $\hat{V}_{\sigma_3}$  nor with one another in the case of intersecting edges.

A natural way to promote the spatial Laplacian to a quantum operator would therefore be to regard it as a function of these basic geometric observables. In d = 2 + 1, on states with simplicial combinatorics, that is 3-valent graphs  $\Gamma$ , this is fairly straightforward as the commuting set of length operators captures the whole simplicial geometry. Thus the two-dimensional spatial Laplacian  $\Delta_2$ can be formally quantized as a composition of length operators,

$$\widehat{\Delta_2} = \Delta_2[\widehat{l_{\sigma_1}}]. \tag{6.3}$$

In practice, to avoid the issue of zeros in the denominator in either the barycentric or circumcentric description, a regularization<sup>14</sup> or linearization of the classical expression  $\Delta_2[l_{\sigma_1}]$  (eq. (5.2) or (5.3)) is needed to achieve a well-defined operator  $\Delta_2[\hat{l_{\sigma_1}}]$ .

In d = 3 + 1 this quantization cannot work as easily because the commuting set of operators  $\widehat{A_{\sigma_2}^2}$  and  $\widehat{V_{\sigma_3}}$  is not sufficient to determine a simplicial spatial geometry. Therefore, the quantum Laplacian  $\widehat{\Delta_3}$  can only be expressed as a function of operators at least a pair of which are non-commuting. A consequence is that  $\widehat{\Delta_3}$  cannot be diagonalized in the spatial geometry states on a given graph. This fact is less problematic than it may look at first sight. Ultimately, pure states of quantum geometry cannot be expected to have a geometry in a classical, e.g., simplicial sense. Only semi-classical coherent states peaked on a classical geometry are supposed to have this meaning. On such states it should be possible to obtain a well-defined action and expectation value of  $\widehat{\Delta_3}$ .

Since we do have expressions of  $\Delta_3$  in three dimensions in terms of face normals (eq. (5.15) and so on), that is fluxes in the canonical setting, an appropriate type of coherent states to be used are those in flux variables studied in [81, 82]. As  $\widehat{\Delta}_3$  is now built from non-commuting operators, there are also ordering ambiguities, and the same issue of regularization of possible inverse volume divergences will also have to be dealt with.

#### Comparison with other proposed Laplacians in the LQG context

We will close this subsection discussing briefly our Laplacian with other proposals appeared in the LQG literature, usually defined in the context of matter Hamiltonians. These proposals are indeed different from ours.

From the Hamiltonian of a non-relativistic point particle on an LQG space, one can read off the following Laplacian  $\widehat{\Delta}_3$  [19]. Assuming that the Hamiltonian is diagonal in the Hilbert space of spin network states  $|s\rangle$ , the result of a discretization procedure is (in the notation of [19])

$$\widehat{\Delta_3} \sim \sum_{s,l \in s} A_l^2 |s, \underset{\sim}{l} \rangle \langle s, \underset{\sim}{l} | \tag{6.4}$$

<sup>&</sup>lt;sup>14</sup>In [79], for example, a Tikhonov regularization [80] is used to cure inverse-volume issues.

on a position basis of the particle on the links of the graph  $|l\rangle$ , where the underlining with a tilde indicates that an inverse-volume factor is included in the definition of this basis.

In the position basis of dual points  $\hat{\sigma}_0$  (dual to primal simplices) natural for the dual scalar function, its expectation value on a spin network state  $|s\rangle$  is

$$\langle s | \widehat{\Delta_3} | s \rangle \sim \sum_{\sigma} \sum_{\sigma' \sim \sigma} \frac{A_{\sigma\sigma'}^2}{V_{\sigma}^2} | \sigma \rangle \langle \sigma | - \sum_{\sigma} \sum_{\sigma' \sim \sigma} \frac{A_{\sigma\sigma'}^2}{V_{\sigma} V_{\sigma'}} | \sigma \rangle \langle \sigma' | , \qquad (6.5)$$

where  $A_{\sigma\sigma'} = V_{\sigma\cap\sigma'}$  are the areas of the primal faces dual to the links connecting  $\sigma$  and  $\sigma'$ .

Obviously, this differs from the Laplacian operator coming from discrete calculus. If the inverse volumes are understood to belong to the position states, the above expression is just a graph Laplace matrix with weights  $A_{\sigma\sigma'}^2$ . This is the definition used in [19]. On the other hand, for the Laplacian to have the right dimension the volumes would have to be considered as part of the its definition (and not of the position basis) and the weights are then, as in the formula above,  $A_{\sigma\sigma'}^2/(V_{\sigma}V_{\sigma'})$ . The advantage of the first choice of position basis and Laplacian with exclusive dependence on the areas, for an application to LQG, is that this Laplacian only needs, for its evaluation, the geometric information that is present in pure spin network states, by passing the issues discussed in the previous section. On the other hand, one might then question whether this choice captures the whole geometric content of the Laplacian, as the one coming from discrete calculus does, and gives an operators with the right properties. Our analysis would suggest that this is not the case, but the above simpler operator could nevertheless represent a useful approximation in some contexts.

A Laplacian of a similar type was also considered in [23] in the context of an evaluation of the spectral dimension in LQG and spin foams. More precisely, the scaling of the Laplacian was all that was needed in that setting, and it was taken to be given just by the area spectrum, so that in practice it amounted as dealing with a diagonal Laplacian.

Another LQG Laplacian appears in [12], within the Hamiltonian for a scalar field. In order to deal with the issue of inverse volumes, one uses Thiemann's trick of substituting inverse 3-volumes with Poisson brackets of holonomies and (powers of) 3-volumes. The Laplacian operator then takes the form

$$\left(\widehat{\Delta}_{3}\phi\right)_{\hat{\sigma}_{0}} \sim \frac{N(\hat{\sigma}_{0})}{E(\hat{\sigma}_{0})^{2}} \sum_{\substack{\Delta \\ v_{\Delta} = \hat{\sigma}_{0}}} \operatorname{tr}(\hat{h}[\hat{h}^{-1}, \hat{V}^{\frac{3}{4}}])^{4} (\phi_{s(\Delta)} - \phi_{\hat{\sigma}_{0}}),$$
(6.6)

where  $N(\hat{\sigma}_0)$  and  $E(\hat{\sigma}_0)$  are some combinatorial factors depending on the vertex  $\hat{\sigma}_0$ , h is the holonomy operator and the sum effectively runs over neighbors, too. The precise structure, in particular of the spectrum, is not known, so a more detailed comparison with the Laplacian coming from discrete calculus, from which it clearly differs, is not possible.

#### 6.2 Laplacian in covariant models

In covariant theories of quantum gravity, the Laplacian lives in spacetime itself rather than on spatial slices only. Even for the spatial Laplacian in LQG, a covariant counterpart in terms of a spin-foam model might be necessary to evaluate it within a physical scalar product.

Such covariant approaches are typically formulated as discretized path integrals. The sum over 4-geometries for a given boundary 3-geometry is defined for geometries on a simplicial pseudomanifold K (e.g., in Regge calculus), or on its dual complex (e.g., in spin-foam models, which can also be re-expressed as simplicial gravity path integrals), and may include a sum over these combinatorial structures as well (dynamical triangulations and group field theories). We discuss briefly the templates for the evaluation of the discrete Laplacian as a geometric observable in these contexts.

#### Quantum Regge calculus

The formalism of discrete calculus is most easily applied to the Regge approach. This is, first of all, because Regge calculus works directly on a simplicial pseudo-manifold K. Second, because the configuration space summed over consists only of simplicial geometries, even in the quantum version. In the latter, this condition has to be imposed by special constraints, namely, the strict generalized triangle inequalities. These demand the volumes of all *p*-simplices to be positive,  $V_{\sigma_p} >$ 0. On such simplicial geometries the discrete Laplacian is automatically well defined (no issues with degeneracies or singularities). Neither in edge length variables  $l_{ij}^2$  nor in the (d-1)-face normal variables  $\omega$  there are any problems in expressing the Laplacian as a classical observable in Regge calculus.

In principle, one could therefore go straight to the quantum theory on a given triangulation |K| in the path integral formulation, given an appropriate measure  $\mu_{\text{Regge}}^{|K|} = [\mathcal{D}l_{ij}] e^{iS_{\text{Regge}}[l_{ij}]}$  or  $\mu_{\text{Regge}}^{|K|} = [\mathcal{D}U_{\alpha\beta}][\mathcal{D}\omega_{\alpha\beta}] e^{iS_{\text{Regge}}[U_{\alpha\beta},\omega_{\alpha\beta}]}$ , and consider the quantum expectation value

$$\langle f[\Delta_d] \rangle^{|K|} = \int \mu_{\text{Regge}}^{|K|} f[\Delta_d].$$
 (6.7)

While the Regge action  $S_{\text{Regge}}$  is well known in both cases, the definition of the exact measure of such a model of quantum gravity is still a pending challenge, with respect to the imposition of the generalized triangle inequalities as well as the issue of simplicial symmetries [8, 83].

## Spin-foams and related path integrals

This path integral expectation value can be considered also in spin-foams, an approach generalizing the concept of Regge geometries [84] where a precise form of the measure can be motivated from a discretization of the Holst–Plebanski action.

By the motivation of spin-foams as a path integral version of LQG defined via spatial graphs  $\Gamma$ , that is 1-complexes, the discrete counterpart of spacetime is usually defined as a 2-complex C (hence the name "foam"). Analogously to the discussion of the canonical case, in a strict sense the discrete Laplacian  $\Delta_d$  is therefore applicable only to 2-complexes being the 2-skeleton of a dual *d*-complex,  $C = (\star K)_2$ . In spin-foams only (d + 1)-valent vertices are considered such that the primal complex K would be indeed a simplicial complex. Nevertheless, an expression of the simplicial  $\Delta_d$  could still be generalized to the setting of arbitrary 2-complexes C, as long as they are equipped with enough geometric data for all the volumes in  $\Delta_d$  to be defined.

Just as in LQG, the geometry variables could be fluxes, holonomies, or their spin representations of the full gauge group G on the edges  $\hat{\sigma}_1 \in \mathcal{C}$ . A spin-foam in the strict sense of the name refers to the latter. Most generally, it is defined as a path-integral state sum over representations  $j_{\hat{\sigma}_2}$  and intertwiners  $i_{\hat{\sigma}_1}$  by a measure factorizing into amplitudes  $\mathcal{A}_{\sigma_p}$  on faces, edges and vertices on  $\mathcal{C}$  [5]:

$$Z^{\mathcal{C}} = \sum_{\{j_{\hat{\sigma}_{2}}\},\{i_{\hat{\sigma}_{1}}\}} \mu_{\mathrm{SF}}^{\mathcal{C}}$$
  
= 
$$\sum_{\{j_{\hat{\sigma}_{2}}\},\{i_{\hat{\sigma}_{1}}\},\hat{\sigma}_{2}\in\mathcal{C}} \prod_{\hat{\sigma}_{2}} \mathcal{A}_{\hat{\sigma}_{2}}(j_{\hat{\sigma}_{2}}) \prod_{\hat{\sigma}_{1}\in\mathcal{C}} \mathcal{A}_{\hat{\sigma}_{1}}(j_{\hat{\sigma}_{2}},i_{\hat{\sigma}_{1}}) \prod_{\hat{\sigma}_{0}\in\mathcal{C}} \mathcal{A}_{\hat{\sigma}_{0}}(j_{\hat{\sigma}_{2}},i_{\hat{\sigma}_{1}}).$$
(6.8)

On the other hand, this is just the spin-foam representation of an underlying more general path integral which could equally well be expressed in holonomies g or fluxes X with corresponding measures:

$$Z^{\mathcal{C}} = \int \left[\mathcal{D}g_{\hat{\sigma}_1}\right] \mu_g^{\mathcal{C}} = \int \left[\mathcal{D}X_{\hat{\sigma}_1}\right] \mu_X^{\mathcal{C}}.$$
(6.9)

Since these variables are directly related to the LQG variables in the canonical theory, the discussion of the possibility to express the Laplacian through them is similiar. Particularly simple

is the d = 3 case of the so-called Ponzano–Regge model with a measure  $\mu_{PR}^{c}$  defined in terms of the dimension of representations associated with edges of the dual complex and of 6*j*-symbols associated with vertices [85]. From the length operator in LQG, an interpretation of primal lengths dual to the foam faces  $\hat{\sigma}_2$  can be induced such that

$$l_{\sigma_1}^2 = l_{\star \hat{\sigma}_2}^2 = j_{\hat{\sigma}_2}(j_{\hat{\sigma}_2} + 1) + c.$$
(6.10)

This defines  $\Delta_3 = \Delta_3(j_{\hat{\sigma}_2})$  on C in its edge length version (eq. (5.2) or (5.4)) and one has a formal expectation value of functions of the Laplacian:

$$\langle f[\Delta_3] \rangle_{\mathrm{PR}}^{\mathcal{C}} = \sum_{\{j_{\hat{\sigma}_2}\}} \mu_{\mathrm{PR}}^{\mathcal{C}} f[\Delta_3(j_{\hat{\sigma}_2})] \,. \tag{6.11}$$

It is then straightforward generalizing to the well-understood case with LQG spin network states  $|s\rangle$  on the boundary of C, where the state sum is running only over internal labels with fixed boundary configurations induced from  $|s\rangle$  [86].

As already noticed, the geometric interpretation of spin-foam configurations is more general than Regge geometries. While the trivial intertwiners  $i_{\hat{\sigma}_1} = i_{\star \sigma_2}$  implicit in the 6*j*-symbols constraint the primal triangles  $\sigma_2$  to close, there are no conditions for the tetrahedra  $\sigma_3$  (more generally, top-dimensional simplices) to close, too. Therefore, the volumes  $V_{\sigma_3}(l_{\sigma_1}^2)$  might take complex values or even vanish. Since they appear in the denominator of the Laplace matrix elements (eq. (5.2)), this may result in poles of the Laplacian.

In d = 4 it is more challenging to get a version of  $\Delta_4$  in terms of the spin representation labels via the LQG-induced relation to primal areas  $A_{\sigma_2}$  (dual to foam faces  $\hat{\sigma}_2$ ) and 3-volumes  $V_{\sigma_3}$  (dual to foam edges  $\hat{\sigma}_1$ ). While the number of labels is in principle large enough, the issue of configurations not uniquely specifing a simplicial geometry discussed above becomes relevant again. A convenient set of variables in which to compute the expectation value of  $\Delta_4$  is obtained in the flux representation of the state sum, that takes then the form of a *BF*-like simplicial path integral. The fluxes  $X_{\hat{\sigma}_2}$  are now the volume forms of primary faces  $\sigma_2$ , that can also be equivalently associated with their dual faces  $\hat{\sigma}_2 = \star \sigma_2$  in the foam.

A general remark is the following. In any discrete path integral, whether configurations on which  $\Delta_d$  is divergent lead to divergences of the overall sum over quantum geometric configurations or not depends very much on the dynamics encoded in the measure. If there were divergences, they could be treated with an appropriate regulator or, when possible, by directly excluding the singular configurations from the path integral. On the other hand, many spin-foam amplitudes are generically divergent even before inserting other geometric observables, and some regularization/renormalization might be needed from the start, anyway. Proper calculations of Laplacianbased observables would have to be then phrased in this regularized context. We will do this in future work.

# 7 Conclusions and outlook

We have employed discrete calculus, known from computational science [36, 38], as a formalism for differential operators and arbitrary fields at a fundamentally discrete level, more precisely on simplicial complexes and their topological dual complexes. This should open up novel ways to investigate the physical and geometric properties of simplicial theories of quantum gravity.

With respect to [36], we chose a different, more physical convention where a geometric space measure is explicitly taken into account. The formalism was presented in a convenient bra-ket

notation and, therefore, slightly generalized, thus providing a setting to rigorously define a discrete Laplacian operator  $\Delta$ . We analyzed the action of the Laplacian on scalar fields living on vertices of the dual complex. The discrete Laplacian can be required to satisfy several properties, coming from continuum properties, from usual lattice gauge theory, from the fractal literature or from reasonable physical requirements. Whether these properties are satisfied or not by the discrete Laplacian we considered depends on the precise geometric embedding of the dual complex into the primal one. In particular, we have shown that the barycentric version may be preferred to the circumcentric one because it does lead to a positivity property that is the discrete counterpart of Osterwalder–Schrader positivity.

The formalism can be made sufficiently general to be extended to polyhedral complexes and complexes with boundary. Also, the Laplacian enters the definition of an invertible momentum transform to a representation of fields on its eigenspaces. This generalization of the Fourier transform works on arbitrary discrete geometries and can be effectively used to handle functions of the Laplacian such as the heat kernel and, from that, the spectral dimension of spacetime. The latter will be the subject of a companion paper [35]. The use of (functions of) the discrete Laplacian as a geometric observable to unravel the geometry of quantum gravity states and histories is indeed one application we envisage for our results. Another application is as a necessary ingredient for defining matter coupling in discrete models of quantum gravity.

These results are ready to be applied to various gravity approaches. We gave explicit expressions of the Laplacian in geometric variables used in loop quantum gravity, spin-foams, Regge calculus and dynamical triangulations: edge lengths, face normals, fluxes, area-angle variables. We discussed how to apply these expressions to specific models, either in a canonical or covariant formalism, and the issues to be tackled. Fluxes seems to be the type of variables with the most general applicability, i.e., for combinatorics other than those of *d*-complexes, as they can be used to define general polyhedral geometries. Operator issues about inverse volumes and dual lengths (present inside  $\Delta$ ) could be cured in various ways: in canonical theory, by regularization or linearizations; in the covariant one by regularization, renormalization precedures or appropriate modifications of models. At any rate, we also noticed that considering functions of the Laplacian, rather than the Laplacian itself, may make these issues irrelevant for practical purposes, as discussed in the example of the heat kernel and in [35]. In particular, the spectral dimension in LQG and spin-foam models can be computed and is well defined.

We conclude with a comment on the continuum limit. In continuum flat space, the discrete Laplacian (3.8) reduces to the second-order continuum Laplace operator:

$$\Delta \to \sum_{\mu=1}^{d} \partial_{\mu}^{2} \,. \tag{7.1}$$

However, the limit to the continuum in a discrete quantum gravity model is much less trivial, because it must include quantum dynamics, a wealth of geometric information (curvature, effective measures respecting quantum symmetries, and so on), and physical matter fields. Thus, the correct physical description of a quantum geometry in a large-scale/low-energy/semi-classical regime may remain elusive in several interesting cases.

The diffusion equation is a crystalline example in this respect. In a discrete setting, it is defined via a test field  $\phi$  obeying  $(\partial_{\tau} - \Delta)\phi = 0$ , with some initial condition  $\phi|_{\tau=0}$  in the abstract diffusion time and where curvature effects are ignored [31, 33, 59]. In the naive sense of eq. (7.1), this equation reduces to the continuum diffusion equation in flat Euclidean space, with the consequence that the spectral dimension of the continuum manifold  $\mathbb{R}^d$  on which the diffusion process takes place is the classical one d. However, if one first computes the effective spectral dimension in a genuinely discrete (and quantum) setting (such as causal dynamical triangulations, for instance [20], or spin-foams [23, 25, 28, 35]), and taking into account the full quantum dynamics, the output would differ from d at any given scale, even in semi-classical or continuum approximations and even in the zero-curvature limit.  $\mathbb{R}^d$  is not necessarily the effective manifold  $\mathcal{M}_{\text{cont}}$  representing the physical continuum limit of the quantum-fluctuating geometry in the large scale regime. As briefly discussed in section 3.2, the physical continuum limit is a black-box procedure which can generate also effective continuous Laplacians (in the sense of the operator governing diffusion processes) which may violate one or more of the properties of the discrete  $\Delta$ , and of the standard continuum one, including locality and the effective order of the operator [33, 59].

The task of getting control over this important aspect of quantum gravity models goes beyond the scope of the present work. Yet, the stage in which this issue can be tackled in the near future has been hopefully improved by the results presented here.

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## A Laplacians on fractals

In the spectral theory of deterministic fractals, Laplacians are defined as a limit of Laplace matrices  $\Delta^{\Gamma_m}$  on a series of graphs  $\Gamma^m$  approximating the fractal which can then be identified with  $\lim_{m\to\infty} \Gamma^m$ . In general [54], one defines Laplacians  $-\Delta^{\Gamma_m}$  on the vertex set of the graphs  $\Gamma^m$  as symmetric linear operators with three properties: Positive definiteness, the null condition and the Markov property. These are exactly the conditions satisfied by the barycentric version of the discrete Laplacian presented in section 3.2, since positive definiteness follows from symmetry and positivity [53].

The graph Laplacian  $\Delta^{\Gamma_m}$  needs two modifications to define the Laplacian on the fractal: A "renormalization factor"  $r^{-m}$  according to the graph approximation, and a volume factor  $V_{\hat{\sigma}_0}^{(m)}$  for the evaluation of a function at a point on the graph  $\hat{\sigma}_0 \in \Gamma^m$ , similar to discrete calculus. The volume factor depends on the self-similar (space) measure  $\mu$  on the fractal, since

$$\langle \hat{\sigma}_0 | \Delta^{\Gamma_m} | \phi \rangle = \int d\mu \ \chi_{\hat{\sigma}_0} \Delta^{\Gamma_m} \phi = \int d\mu \ \psi_{\hat{\sigma}_0}^{(m)} \Delta^{\Gamma_m} \phi$$

$$\approx \left( \int d\mu \ \psi_{\hat{\sigma}_0}^{(m)} \right) \left( \Delta^{\Gamma_m} \phi \right)_{\hat{\sigma}_0} =: V_{\hat{\sigma}_0}^{(m)} \left( \Delta^{\Gamma_m} \phi \right)_{\hat{\sigma}_0}.$$
(A.1)

Here the characteristic function  $\chi_{\hat{\sigma}_0}$  for  $\hat{\sigma}_0$  on the fractal is approximated by the so-called harmonic splines  $\psi_{\hat{\sigma}_0}^{(m)}$ , which are functions sufficiently peaked on  $\hat{\sigma}_0$  on the fractal and identical to the Dirac distribution on the graphs  $\Gamma^m$  [87].

Eventually, the Laplacian on the fractal is defined as the limit

$$(\Delta\phi)_{\hat{\sigma}_0} := \lim_{m \to \infty} \frac{1}{V_{\hat{\sigma}_0}^{(m)} r^m} \left\langle \hat{\sigma}_0 | \Delta^{\Gamma_m} | \phi \right\rangle . \tag{A.2}$$

While the volume factor in the known and understood examples of deterministic fractals is just an overall constant independent of the approximation level m, the exact renormalization factor is crucial to obtain a neither vanishing nor trivial Laplacian [87].

# **B** Geometric data of simplices

For a simplicial complex K with a geometric realization as a piecewise linear space, the frame field can be considered as a set of discrete edge vectors

$$e^{I} = e^{I}_{\mu} \mathrm{d}x^{\mu} \quad \mapsto \quad e^{I}_{ij}(\alpha) = \left[x_{i}(\alpha) - x_{j}(\alpha)\right]^{I} , \qquad (B.1)$$

where the coordinates  $x(\alpha)$  are given by a choice of origin and frame for every *d*-simplex  $\sigma^{\alpha}$  the edge (ij) is face of. The index  $\alpha = 1, 2, ..., N_d$  labels the *d*-simplices. Accordingly, the volume form of a *p*-simplex  $\sigma_p$  in the coordinates of a *d*-simplex it is a face of is

$$\omega_{I_{p+1}\dots I_d}^{\sigma_p}(\alpha) = \epsilon_{I_1\dots I_d} \prod_{k=1}^p e_k^{I_k}(\alpha) , \qquad (B.2)$$

in terms of p linear independent edge vectors  $e_k$  belonging to  $\sigma_p$ . The p-volume  $\sigma_p$  is the norm of the volume form,

$$V_{\sigma_p} = |\omega^{\sigma_p}| = \frac{1}{p!} \sqrt{\sum_{I_{p+1} < \dots < I_d} \left| \omega_{I_{p+1} \dots I_d}^{\sigma_p} \right|^2}.$$
 (B.3)

## B.1 Edge length variables

In the edge length variables  $\{l_{ij}^2\}$ , the volumes can be obtained from the Cayley–Menger determinant

$$V_{\sigma_p} = \frac{1}{p!} \frac{(-1)^{\frac{p+1}{2}}}{2^{\frac{p}{2}}} \begin{vmatrix} 0 & 1 & \cdots & 1 \\ 1 & 0 & l_{ij}^2 & \cdots \\ \vdots & l_{ij}^2 & \ddots & \\ 1 & \vdots & 0 \end{vmatrix}^{\frac{1}{2}}.$$
 (B.4)

In particular,

$$V_{\sigma_2} = \frac{1}{4} \sqrt{\sum_{i} \left( 2l_{ij}^2 l_{ik}^2 - l_{jk}^4 \right)}$$
(B.5)

and, after some manipulations,

$$V_{\sigma_3} = \frac{1}{12} \sqrt{\sum_{(ij)} l_{ij}^2 \left( l_{ik}^2 l_{jl}^2 + l_{il}^2 l_{jk}^2 - l_{ij}^2 l_{kl}^2 \right) - \sum_{(ijk)} l_{ij}^2 l_{ik}^2 l_{jk}^2}, \qquad (B.6)$$
$$V_{\sigma_4} = \frac{1}{96} \left[ \sum_{(ij)(kl)} l_{ij}^4 l_{kl}^4 + \sum_{(ij)(k)} \left( l_{li}^2 l_{ik}^2 l_{kj}^2 l_{jm}^2 + l_{mi}^2 l_{ik}^2 l_{kj}^2 l_{jl}^2 - l_{ij}^4 l_{kl}^2 l_{km}^2 \right) - 2\sum_{(ijkl)} l_{ij}^2 l_{jk}^2 l_{kl}^2 l_{li}^2 - 4\sum_{(ij)} l_{ij}^2 l_{kl}^2 l_{kl}^2 l_{mk}^2 \right]^{\frac{1}{2}}, \qquad (B.7)$$

where all sums run over all subsimplices of the given kind.

## B.2 Barycentric dual volumes

The dual volumes are much more involved and we will consider only dual lengths. In the barycentric case, the length  $\hat{l}_i^{\sigma}$  of the part in one simplex  $\sigma_d = (012...d)$  of an edge dual to the face  $\sigma_{d-1} = (012...\hat{i}...d)$  is given by

$$\hat{l}_{i}^{\sigma} = \frac{1}{d(d+1)} \sqrt{d\sum_{j} l_{ij}^{2} - \sum_{(jk)} l_{jk}^{2}}.$$
(B.8)

This can be seen as follows. In coordinates x the position of the barycenter  $x_{bc}$  of a p-simplex is

$$x_{bc} = \frac{1}{p+1} \sum_{i=0}^{p} x_i \,. \tag{B.9}$$

The distance from the barycenter of  $\sigma_d$  to the barycenter of  $\sigma_{d-1} = (12...d)$  in these coordinates then is

$$\hat{l}_{0}^{\sigma} = \left| \frac{1}{d+1} \sum_{i=0}^{d} x_{i} - \frac{1}{d} \sum_{i=1}^{d} x_{i} \right| = \left| d x_{0} - \frac{1}{d(d+1)} \sum_{i=1}^{d} x_{i} \right|,$$
(B.10)

and choosing coordinates where  $x_0$  is the origin and using  $x_i \cdot x_j = g_{ij} = \frac{1}{2} \left( l_{0i}^2 + l_{0j}^2 - l_{ij}^2 \right)$  [88] this reduces to

$$\hat{l}_{0}^{\sigma} = \frac{1}{d(d+1)} \sqrt{\left(\sum_{i=1}^{d} x_{i}\right)^{2}} = \frac{1}{d(d+1)} \sqrt{\sum_{i} x_{i}^{2} - 2\sum_{(ij)} x_{i} \cdot x_{j}}$$
$$= \frac{1}{d(d+1)} \sqrt{d\sum_{i} l_{0i}^{2} - \sum_{(ij)} l_{ij}^{2}}.$$
(B.11)

Besides the simple two dimensional case this formula was also proven before for the tetrahedron (theorem 187 in [89]).

## B.3 Circumcentric dual volumes

In the circumcentric case, in d = 2 one gets dual edge lengths from the circumradius  $R_{ijk} = \frac{l_{ij}l_{ik}l_{jk}}{4A_{ijk}}$ :

$$\hat{l}_{jk}^{(ijk)} = \sqrt{R_{ijk}^2 - \left(\frac{l_{jk}}{2}\right)^2} = \frac{l_{jk}}{2} \sqrt{\frac{l_{ij}^2 l_{ik}^2}{4A_{ijk}^2} - 1}$$
$$= \frac{l_{jk}}{4A_{ijk}} \sqrt{l_{ij}^4 + l_{jk}^2 + l_{ki}^2 - l_{ij}^2 l_{ik}^2 - 2(l_{jk}^2 l_{ij}^2 + l_{jk}^2 l_{ik}^2)}.$$
(B.12)

Since

$$4l_{jk}^{2}l_{ik}^{2} - 16A_{ijk}^{2} = l_{ij}^{4} + l_{jk}^{4} + l_{ki}^{4} - 2(l_{jk}^{2}l_{ij}^{2} + l_{jk}^{2}l_{ik}^{2} - l_{ij}^{2}l_{ik}^{2})$$
  
=  $(l_{ij}^{2} + l_{ik}^{2} - l_{jk}^{2})^{2}$ , (B.13)

this simplifies to

$$\hat{l}_{jk}^{(ijk)} = \frac{l_{ij}^2 + l_{ik}^2 - l_{jk}^2}{4A_{ijk}} \frac{l_{jk}}{2}.$$
(B.14)

The matrix elements of the Laplacian are

$$\frac{w_{(ijk)(jkl)}}{A_{ijk}} = \frac{1}{A_{ijk}} \frac{2}{\pm \sqrt{\frac{l_{ij}^2 l_{ik}^2}{4A_{ijk}^2} - 1} \pm \sqrt{\frac{l_{jl}^2 l_{kl}^2}{4A_{jkl}^2} - 1}}_{4}$$
(B.15)

$$= \frac{1}{\pm \sqrt{l_{ij}^2 l_{ik}^2 - 4A_{ijk}^2 \pm \frac{A_{ijk}}{A_{jkl}} \sqrt{l_{jl}^2 l_{kl}^2 - 4A_{jkl}^2}}} = \frac{8}{\pm \left(l_{ij}^2 + l_{ik}^2 - l_{jk}^2\right) \pm \frac{A_{ijk}}{A_{jkl}} \left(l_{jl}^2 + l_{kl}^2 - l_{jk}^2\right)}.$$
 (B.16)

For d = 3, there is a formula relating the circumradius R of the tetrahedron (ijkl) to the area  $\mathcal{A}_{ijkl}$  of a triangle with the product of opposite edge lengths in the tetrahedron as its edge lengths [89]:

$$6V_{ijkl}R_{ijkl} = \mathcal{A}_{ijkl} \,. \tag{B.17}$$

The circumcentric dual length to a face (ijk) thus is

$$\hat{l}_{\hat{l}}^{(ijkl)} = \sqrt{R_{ijkl}^2 - R_{ijk}^2} = \frac{\sqrt{(2A_{ijk}\mathcal{A}_{ijkl})^2 - (3l_{ij}l_{jk}l_{ki}V_{ijkl})^2}}{12A_{ijk}V_{ijkl}}, \qquad (B.18)$$

and the Laplace weight

$$w_{(ijkl)(ijkm)} = \frac{12A_{ijk}^2 V_{ijkl}}{\sqrt{(2A_{ijk}\mathcal{A}_{ijkl})^2 - (3l_{ij}l_{jk}l_{ki}V_{ijkl})^2} + V_{ijkl}\sqrt{\left(\frac{2A_{ijk}\mathcal{A}_{ijkm}}{V_{ijkm}}\right)^2 - (3l_{ij}l_{jk}l_{ki})^2}}.$$
 (B.19)

A simplification to avoid the square roots, as in d = 2, remains to be found.

## C Simple example: degenerate triangulation of the *d*-Sphere

To illustrate the formalism we consider as an example the triangulation of the *d*-sphere  $S^d$  by two *d*-simplices labeled a, b with the same vertices  $1, 2, \ldots, d+1$  which are glued along all their faces  $(1, \ldots, \hat{i}, \ldots, d+1)$ . The weights of the Laplacian are  $w_{(1,\ldots,\hat{i},\ldots,d+1)} = V_{(1,\ldots,\hat{i},\ldots,d+1)}/V_{\star(1,\ldots,\hat{i},\ldots,d+1)}$  but in the end only the degrees  $D = D_a = D_b = \sum_{(1,\ldots,\hat{i},\ldots,d+1)} w_{(1,\ldots,\hat{i},\ldots,d+1)}$  enter in this specific example:

$$(\Delta\phi)_a = \frac{1}{V_a} \sum_{(1,\dots,\hat{i},\dots,d+1)} w_{(1,\dots,\hat{i},\dots,d+1)} \left(\phi_a - \phi_b\right) = \frac{D}{V_a} \left(\phi_a - \phi_b\right) \,, \tag{C.1}$$

and for the simplex b accordingly. The eigenvalues of the Laplacian are  $\lambda_0 = 0$  and  $\lambda_1 = V D/(V_a V_b)$ , which directly give the heat trace and spectral dimension.

The eigenvectors  $e_{\sigma}^{\lambda_0} = (1,1)/\sqrt{2}$  and  $e_{\sigma}^{\lambda_1} = (V_b, -V_a)/\sqrt{2V_aV_b}$  are normed to a constant momentum basis measure of the inverse of the average volume per simplex

$$V_{\lambda_0} = V_{\lambda_1} = \frac{2}{V} \,, \tag{C.2}$$

and it is easily checked that they are orthogonal. Then the heat kernel coefficients are

$$K_{\sigma\sigma'}(\tau) = \frac{1}{V} \begin{pmatrix} V_a (1 + \frac{V_b}{V_a} e^{-\frac{V D}{V_a V_b} \tau}) & V_a (1 - e^{-\frac{V D}{V_a V_b} \tau}) \\ V_b (1 - e^{-\frac{V D}{V_a V_b} \tau}) & V_b (1 + \frac{V_a}{V_b} e^{-\frac{V D}{V_a V_b} \tau}) \end{pmatrix},$$
(C.3)

and we can explicitly check that

$$K_{\sigma\sigma'}(\tau) \xrightarrow[\tau \to \infty]{} \begin{pmatrix} \frac{1}{V_a} & 0\\ 0 & \frac{1}{V_b} \end{pmatrix}$$
(C.4)

and that its trace is just

$$\mathcal{P}(\tau) = \frac{1}{V} \left( 1 + e^{-\frac{V D}{V_a V_b} \tau} \right) \,. \tag{C.5}$$

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