Eigenmode in a misaligned triangular optical cavity

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Abstract. We derive relationships between various types of small misalignments on a triangular Fabry-Perot cavity and associated geometrical eigenmode changes. We focus on the changes of beam spot positions on cavity mirrors, the beam waist position, and its angle. A comparison of analytical and numerical results shows excellent agreement. The results are applicable to any triangular cavity close to an isosceles triangle, with the lengths of two sides much bigger than the other, consisting of a curved mirror and two flat mirrors yielding a waist equally separated from the two flat mirrors. This cavity shape is most commonly used in laser interferometry. The analysis presented here can easily be extended to more generic cavity shapes. The geometrical analysis not only serves as a method of checking a simulation result, but also gives an intuitive and handy tool to visualize the eigenmode of a misaligned triangular cavity.

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1. Introduction

Fabry-Perot cavities are widely used in the field of laser interferometry, and longitudinal length shifts of a cavity mirror and the resulting change in the phase of the resonating field is well known. However in the case where suspended mirrors are used, such as in gravitational wave detectors, angular shifts play a crucial role in the detector performance; they ensure clean length control signals. Angular shifts on the cavity mirrors and resulting eigenmode changes in the circulating Gaussian beam of a plane cavity were geometrically analyzed in [1], and the results are used, together with results from simulation work, to obtain error signals to control the alignment of various cavity mirrors. Recently we designed a triangular optical cavity for the purpose of frequency stabilization for the AEI 10 m Prototype [2], and in the process of designing an alignment control system, a geometrical analysis for this cavity was performed. The cavity is close to an isosceles triangle, with the lengths of two sides much bigger than the other, consisting of a curved mirror and two flat mirrors yielding a waist equally separated from the two flat mirrors. However this cavity shape is most commonly used in laser interferometry, the results presented here can easily be extended to more generic cavity

shapes. In this paper we first derive the relations of small mirror misalignments and the resulting changes in the eigenmode. By small misalignments we mean the regime where a lateral shift, and the angular deviation of the waist is smaller than the waist radius, and the divergence angle of the beam, respectively. The results are shown in terms of beam spot position changes on all the cavity mirrors, the waist position changes, and the waist angular shifts. They carry sufficient information for designing an angular control system. We then compare the results with that of two simulation tools, and show that they are in excellent agreement with each other.

2. Types of misalignments

Figure 1 shows the schematic of a triangular cavity when aligned. Two flat mirrors are relatively close together and are labeled as M_a and M_c , while the curved mirror is far away, has a radius of curvature R and is labeled as M_b . The position where the beam hits the mirror M_i is given by P_i , as well as the waist position by P_w , followed by the associated coordinates within the x-y plane. Here, we also introduce a coordinate system attached to each of the flat mirrors $(y_a \text{ and } y_c)$ for convenience. The two equal angles of the beam at M_a and M_c and half the small angle at M_b are given by γ and ϕ , respectively. Due to the shape of the triangle the following approximations hold and are used throughout this paper unless otherwise noted:

$$\gamma \approx \pi/2 \tag{1}$$

$$\phi \ll 1 \tag{2}$$

Angular degrees of freedom in horizontal and vertical directions for the three mirrors produce six modes of misalignments.

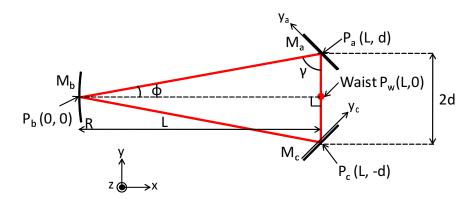


Figure 1. Schematic of an aligned triangular cavity within the x-y plane. Also defined are the two coordinate axes y_a and y_c that are fixed on the flat mirrors M_a and M_c , respectively. Mirror M_b has a radius of curvature of R.

Misalignment angles of mirror M_i are given by α_i and β_i for horizontal (angles around the z-axis, sometimes also called yaw or rotation), and vertical (inclination angle with respect to the x-y plane, sometimes also called pitch or tilt) directions,

Type	Description	Section
α_{-}	Differential of the flat mirrors in horizontal	3.1.
α_b	Curved mirror in horizontal	3.2.
α_{+}	Common of the flat mirrors in horizontal	3.3.
β_b	Curved mirror in vertical	4.1.
β_{+}	Common of the flat mirrors in vertical	4.2.
β_+	Differential of the flat mirrors in vertical	4.3.

Table 1. Summary of types of misalignments and associated section numbers.

respectively. A positive angle is formed by counter-clockwise rotation around the z-axis for horizontal misalignments, and around the y-axis, y_a -axis, and y_c -axis for vertical misalignment of M_b , M_a and M_c , respectively. We take linear combinations of these two flat mirror misalignments to form common and differential modes: $\alpha_{\pm} = (\alpha_a \pm \alpha_c)/2$ and $\beta_{\pm} = (\beta_a \pm \beta_c)/2$. The changes in the waist position and the beam spot position on mirror M_i are denoted by Δk_w and Δk_i , with k being the corresponding x or y coordinates. Ane angular change of the beam between the two flat mirrors is denoted by θ (see Fig. 3. Since we concern small misalignments, these changes are also small. Hence we use the following approximation throughout this paper: $\theta \ll 1$ and $O(\Delta k^n) = 0$ for $n \geq 2$. All types of misalignments are summarized and the associated section numbers are listed in Table 1.

3. Horizontal misalignments

3.1. Misalignment in α_{-}

A misalignment in α_- , i.e. contrary tilts around the z-axis, keep the cavity symmetric to the x-axis and, hence, causes a symmetric change in the eigenmode. In Fig. 2, the original and the new eigenmodes are shown by the lighter (yellow) and darker colors (this color rule is applied throughout this paper), and the x and y coordinates of the spot positions on the mirrors are shown. Because of the symmetry it is obvious that Δx_a equals Δx_c and Δx_w , and due to the approximation given by Equ. 1, Δy_a also equals Δx_a . The angle of incidence on the flat mirrors changes by $\frac{1}{2}\alpha_-$, as indicated by the dashed normal on one mirror surface. The large angle γ' changes by $-\alpha_-$, yielding a change by α_- in half the small angle $\Delta \phi$. From looking at the shaded area in Fig. 2 we get:

$$\Delta y_c \approx \sqrt{L^2 + d^2} \sin \Delta \phi \approx \sqrt{L^2 + d^2} \cdot \Delta \phi = -\sqrt{L^2 + d^2} \cdot \alpha_- \tag{3}$$

Therefore we know the following relations between the spot position changes and the misalignment angle:

$$\Delta x_a = \Delta x_c = -\Delta y_a = \Delta y_c = \Delta x_w = -\sqrt{L^2 + d^2} \cdot \alpha_- \tag{4}$$

and hence the angle deviation θ at the waist is zero.

To summarize, a misalignment in $+(-)\alpha_{-}$ causes a shrink (stretch) of the eigenmode along the x-axis, yielding the eigenmode to keep its isosceles shape, but change its shape in a way that it becomes more "fat" ("thin"). As a result, the waist position shifts in x-direction by an amount that is approximately proportional to the distance between the curved mirror and the two flat mirrors.

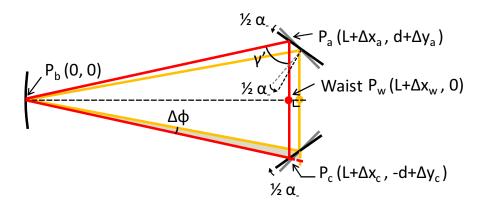


Figure 2. Cavity eigenmodes of the aligned (lighter colored triangle) and the misaligned by α_{-} (darker colored triangle) cases. The contrary tilts around the z-axis cause a symmetric change in the eigenmode.

3.2. Misalignment in α_b

Figure 3 shows a hypothetic misaligned cavity caused by α_b , i.e. a rotation of M_b around the vertical axis. In this case, there is no obvious symmetry axis. One can expect changes in the positions of the beam spots on the mirrors and of the waist, as well as an angle deviation at the waist. We introduce a pivot, where the non-congruent side of the aligned and the misaligned eigenmodes cross, indicated by the thick circle. We start with an arbitrary location of the pivot, and will shortly show that it coincides with the bisecting point of the non-congruent side.

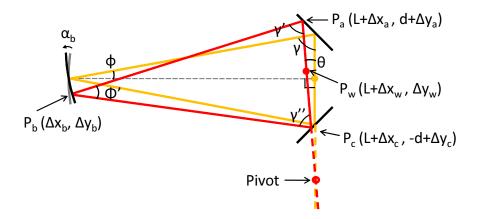


Figure 3. Cavity eigenmodes of the aligned and the misaligned cases by α_b . We start with a general, and hence hypothetical case where the pivot and the bisecting point of the non-congruent do not match, and later show they coincide. The changes of the two larger angles (γ) are of the same size but with opposite sign, hence the small angle ϕ stays unchanged.

The angle of incidence on the flat mirrors changes by the same amount θ , but with opposite sign, resulting in the following changes of the large angles: $\gamma' = \gamma + 2\theta$ and $\gamma'' = \gamma - 2\theta$. Hence the small angle stays unchanged: $\phi' = 2\phi$.

Looking at the flat mirrors, as shown in Fig. 4, and applying the approximation given by

Equ. 1, one sees that $\Delta x_a = -\Delta y_a$ and $\Delta x_c = \Delta y_c$. The following set of equations describe the shift of the spot positions:

$$\Delta x_a = l_a \sin \theta \tag{5}$$

$$\Delta x_c = l_c \sin \theta \tag{6}$$

$$2d = l_a \cos \theta - l_c \cos \theta - |\Delta y_a| - |\Delta y_c| \tag{7}$$

$$= (l_a - l_c)\cos\theta - (|\Delta x_a| + |\Delta x_c|)$$

$$\approx l_a - l_c - (|l_a| + |l_c|)\theta$$
(8)

where l_a and l_c are the distances from the pivot to P_a and P_c along the beam, respectively.

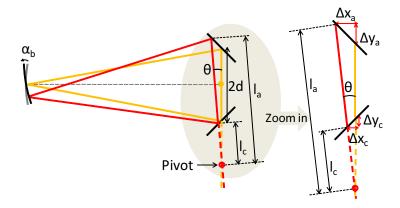


Figure 4. Closer view of the two flat mirrors and the pivot. It still shows the hypothetical eigenmode where the pivot and the bisecting point do not match.

The left hand side of Equation 7 is constant, hence the right hand side must be independent of θ , yielding the following relations:

$$l_a = -l_c \tag{9}$$

$$|l_a| = |l_c| = d/\cos\theta \equiv l \tag{10}$$

$$\Delta x_a = -\Delta x_c = -\Delta y_a = -\Delta y_c = l \sin \theta = d \tan \theta \approx d\theta \tag{11}$$

This automatically means that the pivot (P_p) bisects the non-congruent side, as shown in Fig. 5, where the changes in the location of the pivot is denoted by Δx_p and Δy_p . It also shows the details around the flat mirrors, from which the pivot location with respect to the original waist is given by

$$\Delta x_p = O\left(\theta^2\right) = 0\tag{12}$$

$$\Delta y_p = d - l\cos\theta + \Delta y_a = -d\theta \tag{13}$$

Connecting the beam spot on the curved mirror (P_b) and the bisector point (the pivot, or P_p), one can see that it bisects the beam angle at M_b into ϕ , as shown in Fig. 6. This means that the line passes through the center of curvature, (P_{COC}) , whose coordinate along the y-axis is given by

$$\Delta y_{\rm COC} = R \cdot \alpha_b \tag{14}$$

Focusing on the shaded triangles shown in Fig. 6, one can see that $\theta' = \theta$, and, comparing the two triangles, one can also see that $\theta'' = \theta' = \theta$. The radius vectors of the aligned and

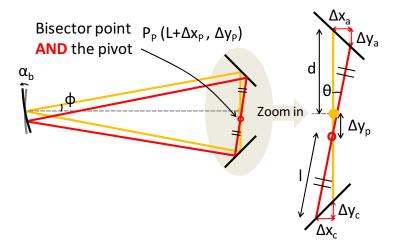


Figure 5. Closer view of the two flat mirrors. Here, the pivot and the bisecting point overlap, and the y coordinate of the pivot is denoted by Δy_p .

misaligned mirror, indicated by the dotted lines in Fig. 6, cross at point P_r . By focusing on the triangle consisting of the original waist (P_w) , the pivot, (P_p) , and P_r , as shown in the lower triangle in Fig. 6, one can see that the x coordinate of the point P_r is given by

$$\Delta x_r = d\theta / \tan \theta \approx d \tag{15}$$

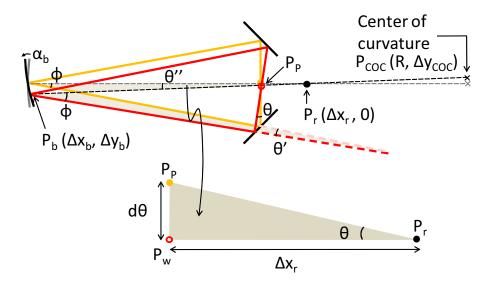


Figure 6. Radius vectors of the aligned and the misaligned cases. They cross at the point P_r , from which the angle deviation and the pivot location are calculated.

Figure 7 lists all the length information that is needed to calculate the angle θ and the spot position on M_b . These are given by the following set of equations:

$$\theta \approx \tan \theta = R \alpha_b / (R - L - d)$$
 (16)

$$\Delta x_b = O\left(\Delta y_b^2\right) = 0\tag{17}$$

$$\Delta y_b = -(L+d) \tan \theta \approx -(L+d) \theta = -R \alpha_b \cdot (L+d) / (R-L-d)$$
 (18)

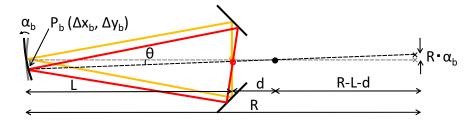


Figure 7. Length information needed to calculate θ and the spot position change on M_b .

Having calculated the new spot positions on the mirrors, we now calculate where the new waist is. In order for the wavefront curvature of the beam to match the radius of curvature of the curved mirror M_b , the path lengths from the waist to the mirror M_b via M_a and via M_c should be the same, i.e. in Fig. 8 it should be $S_a + D_a = S_c + D_c = S + d$. By calculating the distances S_a and S_b in the following equations, we also will obtain the distances D_a and D_b :

$$S_{a} = \left\{ (L + d\theta)^{2} + (d + L\theta)^{2} \right\}^{1/2}$$

$$\approx \sqrt{L^{2} + d^{2}} \left(1 + \frac{4Ld\theta}{L^{2} + d^{2}} \right)^{1/2} \qquad \theta^{2} = 0$$

$$\approx \sqrt{L^{2} + d^{2}} \left(1 + \frac{2Ld\theta}{L^{2} + d^{2}} \right) \qquad \frac{2Ld\theta}{L^{2} + d^{2}} \ll 1$$

$$= S + 2d\theta \qquad d^{2}/L^{2} = 0$$

$$D_{a} = S + d - S_{a} = d - 2d\theta \qquad (20)$$

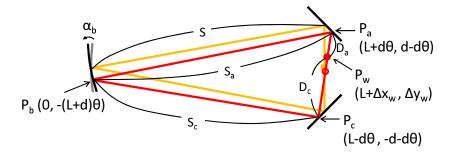


Figure 8. Locations of the new spot positions on the mirrors. By using them the new waist location is calculated.

In a similar way

$$S_c = \left\{ (L - d\theta)^2 + (-d + L\theta)^2 \right\}^{1/2} = S + 2d\theta \tag{21}$$

$$D_c = S + d - S_b = d + 2d\theta \tag{22}$$

Hence, the new waist location is given by the following:

$$\Delta x_w = O\left(\theta^2\right) = 0\tag{23}$$

$$\Delta y_w = (d - d\theta - D_a)\cos\theta \approx d\theta = dR \alpha_b / (R - L - d) \tag{24}$$

To summarize, a misalignment in $+(-)\alpha_b$ causes a clockwise (counter-clockwise) rotation of the non-congruent side around the bisecting point, yielding the long sides to rotate

synchronously. As a result all the beam spot positions change by the amounts given by the radial distances with the bisecting point being the origin of the system of radial coordinates.

3.3. Misalignment in α_+

In the case of $\alpha_+ \neq 0$, there is no obvious symmetry line, thus we will start from a general case. Changes on the spot positions, the beam angle at the waist, and the two larger angles are defined as shown in Fig. 9. Figure 10 focuses on the beam angle change on mirror M_a .

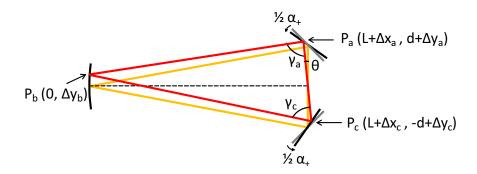


Figure 9. Cavity eigenmodes of the aligned and the misaligned (α_+) cases.

Drawing helping lines such as the one that is parallel to the aligned beam (indicated by the light colored thick dotted line), as well as lines that are normal to both the aligned and the misaligned mirror surfaces (indicated by the light thin, and dark thin dotted lines, respectively) one can see that half of γ_a is given by $\gamma_a/2 = \gamma/2 + \theta - \alpha_+/2$. Hence,

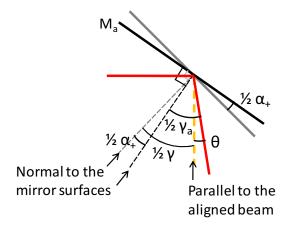


Figure 10. Closer view on the change in one of the larger angles, γ_a .

$$\gamma_a = \gamma + (2\theta - \alpha_+) \tag{25}$$

In a similar manner, γ_c is given by

$$\gamma_c = \gamma - (2\theta - \alpha_+) \tag{26}$$

This means that the sum of the two angles stays unchanged, yielding no change in the small angle ϕ . Then the line that connects P_b with the center of curvature of M_b (from here on this is called the radius), should bisect the short side, due to the fact that $d \ll L$. The bisecting

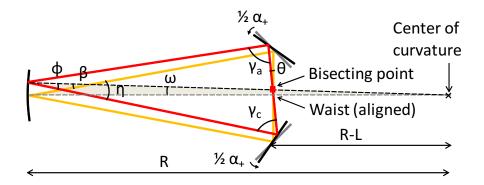


Figure 11. Ancillary angles: β , η and ω , which are use to calculate θ .

point is indicated by the square point in Fig. 11. Here, we introduce some ancillary angles β and η , together with ω , which is the angle of the radius with respect to the aligned case. Focusing on the shaded area, one can see that the ancillary angles are given by

$$\beta = \phi + \omega \qquad \text{and} \tag{27}$$

$$\eta = \phi + \beta = 2\phi + \omega \tag{28}$$

 η can be expressed using γ if one focuses on the shaded triangle shown in Fig. 12, introducing a new ancillary angle $\gamma_a' = \gamma + \theta$, and it is given by

$$\eta = \pi - (\gamma_a' + \gamma_c) = \pi - \{(\gamma + \theta) + \gamma - (2\theta - \alpha_+)\} = \pi - 2\gamma + \theta - \alpha_+$$
(29)

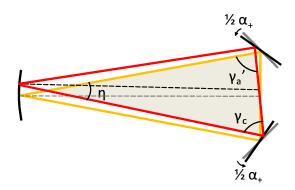


Figure 12. Yet another ancillary angle $\gamma_a^{'}$ to calculate η .

By comparing Equations 28 and 29 the angle ω is given by the following equations:

$$\pi - 2\gamma + \theta - \alpha_{+} = 2\phi + \omega \tag{30}$$

$$\omega = \pi - (2\gamma + 2\phi) + \theta - \alpha_{+} = \theta - \alpha_{+} \tag{31}$$

In order to gain additional information to finally calculate θ , we focus on some lengths as shown in Fig. 13. The pivot (P_p) is indicated by the thick circle and changes in its location are denoted by Δx_p and Δy_p , and the two lengths from the pivot to the two beam spots by l_a and l_b . Changes in the coordinates of the beam spot position on M_a are given by the following equations:

$$\Delta x_a = -l_a \sin \theta \approx -l_a \theta \tag{32}$$

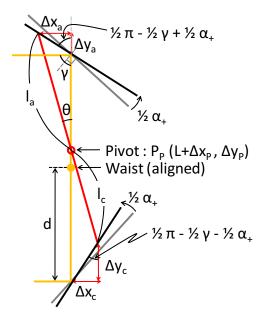


Figure 13. Length relations around the flat mirrors. From this the lengths l_a and l_c from the pivot to the beam spots on the two mirrors are calculated.)

$$\Delta y_a = \frac{-\Delta x_a}{\tan(\pi/2 - \gamma/2 + \alpha_+/2)} \approx \frac{1 - \alpha_+/2}{1 + \alpha_+/2} l_a \theta \approx (1 - \alpha_+) l_a \theta \tag{33}$$

and Δx_c and Δy_c by:

$$\Delta x_c = l_c \sin \theta \approx l_c \theta \tag{34}$$

$$\Delta y_c = \frac{\Delta x_c}{\tan(\pi/2 - \gamma/2 - \alpha_+/2)} \approx \frac{1 + \alpha_+/2}{1 - \alpha_+/2} l_c \theta \approx (1 + \alpha_+) l_c \theta \tag{35}$$

The length of the non-congruent side is then expressed by the following:

$$2d = l_a \cos \theta + \Delta y_a + l_c \cos \theta + \Delta y_c \approx l_a + l_c - \{l_a - l_c - (l_a + l_c) \alpha_+\} \theta \quad (36)$$

Since the left-hand side of Equation 36 does not depend on the misalignment angle θ , the angle dependent term of the right-hand side should be zero, hence,

$$l_a - l_c - (l_a + l_c) \alpha_+ = 0 (37)$$

From Equations 36 and 37 the following relations can be obtained:

$$l_a = d\left(1 + \alpha_+\right) \tag{38}$$

$$l_c = d\left(1 - \alpha_+\right) \tag{39}$$

With this knowledge we can calculate the location of the pivot in the following way:

$$\Delta x_p = O\left(\theta^2\right) = 0\tag{40}$$

$$\Delta y_p = l_c \cos \theta + \Delta y_c - d \approx d(\theta - \alpha_+) \tag{41}$$

The location of the bisecting point, as shown in Fig. 14, can be calculated in a similar way, and the coordinates are given by

$$\Delta x_B = O\left(\theta^2\right) = 0\tag{42}$$

$$\Delta y_B = d \cos \theta + \Delta y_c - d \approx (1 + \alpha_+) (1 - \alpha_+) d\theta \approx d\theta \tag{43}$$

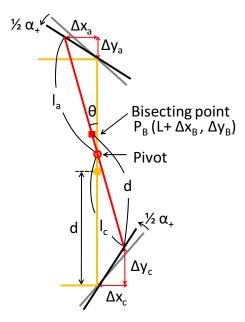


Figure 14. Length relations around the flat mirrors, including the pivot location. From this the spot position changes on the flat mirrors are calculated.

Then, focusing on the triangle that consists of the center of curvature, the waist (in the aligned case), and the bisecting point (indicated by the right part of the shaded area in Fig. 11), one can obtain another relation for ω and θ which is given by

$$\omega \approx \tan \omega = d\theta / (R - L) \tag{44}$$

From Equations 31 and 44 one can finally obtain the relation between θ and α_+ :

$$\theta = \frac{R - L}{R - L - d} \cdot \alpha_{+} \tag{45}$$

Using θ , the spot positions on the three mirrors (see Equations 32, 33, 34, and 35) can further be calculated. This yields the following equations:

$$\Delta x_a = -d(1+\alpha_+)\theta \approx -\frac{d(R-L)}{R-L-d} \cdot \alpha_+ \tag{46}$$

$$\Delta y_a = (1 - \alpha_+) \, \Delta x_a \approx -\frac{d (R - L)}{R - L - d} \cdot \alpha_+ \tag{47}$$

And in similar ways,

$$\Delta x_c = \frac{d(R-L)}{R-L-d} \cdot \alpha_+ \tag{48}$$

$$\Delta y_c = \frac{d(R-L)}{R-L-d} \cdot \alpha_+ \tag{49}$$

and

$$\Delta x_b = O\left(\Delta y_b^2\right) = 0 \tag{50}$$

$$\Delta y_b = R \cdot \omega = R \cdot (\theta - \alpha_+) = \frac{dR}{R - L - d} \cdot \alpha_+ \tag{51}$$

Then the waist location can be calculated in the same way as shown in equations 19 to 24, and the following can be shown:

$$S_a = \left\{ (L + \Delta x_a)^2 + (d + \Delta y_a - \Delta y_b)^2 \right\}^{1/2} \approx S - (d\theta + \Delta y_p)$$
 (52)

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$$D_a = d + d\theta + \Delta y_p \tag{53}$$

In a similar way we obtain

$$S_b = S + (d\theta + \Delta y_p) \tag{54}$$

$$D_b = d - d\theta + \Delta y_p \tag{55}$$

Therefore the new waist location is given by

$$\Delta x_w = O\left(\theta^2\right) = 0 \tag{56}$$

$$\Delta y_w = (d + \Delta y_a - D_a)\cos\theta \approx -\Delta y_p = -\frac{d^2}{R - L - d} \cdot \alpha_+ \tag{57}$$

To summarize, a misalignment in $+(-)\alpha_+$ causes a counter-clockwise (clockwise) rotation of the non-congruent side around a point that does not coincide with the bisecting point. This yields a clockwise (counter-clockwise) rotation ω (which is very small compared to the misalignment angle α_+) of the geometrical axis of a corner reflector consisting of the two flat mirrors. As a result, the eigenmode changes in a "non uniform" way, with each spot position change being smaller than the misalignment case of α_b .

4. Vertical misalignments

When considering vertical misalignments, it is necessary to view the cavity as a 3D body, as shown in Fig. 15. Notations of all the properties are the same as that shown in Fig. 1.

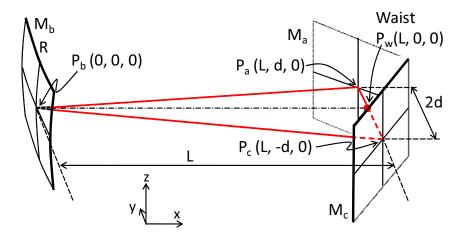


Figure 15. 3D view of a triangular cavity. M_a and M_c are the flat mirrors, and M_b has a radius of curvature of R. The positions where the beam hits the mirror M_i are denoted by P_i .

4.1. Misalignment in β_b

A misalignment around the y-axis by β_b , as shown in Fig. 16, does not affect the mirror alignment in y-direction, hence there is no change in eigenmode in that direction. Then it is possible to project the cavity onto the x-z plane for simplicity, as shown in Fig. 17, and treat it as a plane cavity. The eigenmode of the cavity is defined by the line that is orthogonal to the flat mirrors and passes through the center of curvature, as described in [1]. It is obvious

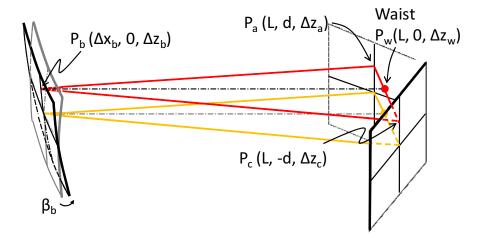


Figure 16. Cavity eigenmodes of the aligned (lighter colored triangle) and the misaligned by β_b (darker colored triangle) cases. This type of misalignment does not affect the mirror alignment in y-direction, hence the eigenmode only changes along the z-axis.

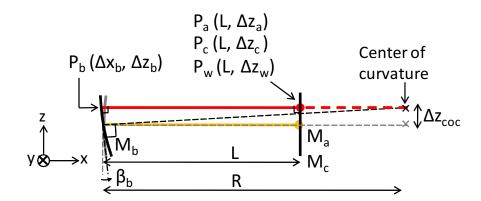


Figure 17. Projection of the triangular cavity onto the x-z plane. It allows one to view the cavity as a plane cavity. The eigenmode is defined by the line that is orthogonal to the flat mirror and passes through the center of curvature.

that the eigenmode is also orthogonal to the curved mirror, yielding the shifts in z-direction of all of the spot positions to have the same size. The normal vector on the mirror M_b is tilted by β_b , hence the center of curvature, whose z coordinate is denoted by $z_{\rm coc}$, shifts by $\Delta z_{\rm coc} = \beta_b \cdot R$. Therefore we have the following relations:

$$\Delta x_a = O\left(\beta_b^2\right) = 0\tag{58}$$

$$\Delta z_a = \Delta z_b = \Delta z_c = \Delta z_w = \Delta z_{\rm coc} = \beta_b \cdot R \tag{59}$$

To summarize, a misalignment in $+(-)\beta_b$ causes an upward (downward) shift of the center of curvature along the z-axis, yielding a synchronous shift of the plane of the eigenmode by an amount proportional to the radius of curvature of the curved mirror.

4.2. Misalignment in β_+

Similar to β_b , β_+ has no effects in y-direction. However, since the y_a -axis and the y_c -axis are rotated by $\pm \left(\frac{\pi}{2} - \frac{\gamma}{2}\right) \approx \pm \frac{\pi}{4}$ around the y-axis, respectively, the projection of a misalignment by $\beta_+/2$ around the two axes becomes $\frac{1}{2}\beta_+/\sqrt{2}$. Section 4.10, (page 100-102) of reference [3], gives a detailed explanation of this effect by using a vector algebra and we will not describe it in this paper. For convenience we introduce an effective misalignment angle $\beta_{\rm eff} = \beta_+/\sqrt{2}$.

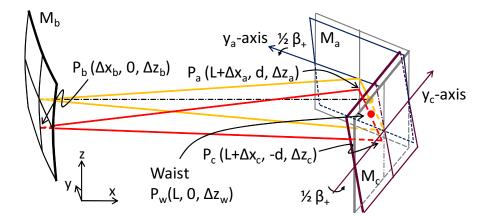


Figure 18. Cavity eigenmodes of the aligned and the misaligned (β_+) cases. This type of misalignment does not affect the mirror alignment in y-direction, hence the eigenmode only changes along the z-axis.

The projection of the flat mirrors are rotated by $\beta_{\rm eff}/2$ around the y-axis and the effect is doubled because of the two reflections, hence, seen as a plane cavity, the misalignment angle is given by $\beta_{\rm eff}$, as shown in Fig. 19. The eigenmode of this cavity is defined by the line

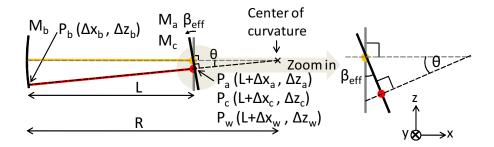


Figure 19. Projection of the triangular cavity onto the x-z plane. It allows one to view the cavity as a plane cavity. The eigenmode is defined by the line that is orthogonal to the flat mirrors and passes through the center of curvature. In the right part, an enlarged cut-out around one flat mirror is shown.

that passes through the center of curvature and intersects the flat mirrors orthogonally, as described in [1]. The angle formed by the eigenmodes of the aligned and misaligned cases is denoted by θ in Fig. 19, and it becomes obvious that $\theta = \beta_{\text{eff}}$ when one focuses around the area of the flat mirrors, as shown in the enlarged cut-out in the right part of Fig 19. Therefore the following equations yield the spot position changes:

$$\Delta x_{a,b,c,\,\text{and}\,w} = O\left(\beta_+^2\right) = 0 \tag{60}$$

Eigenmode in a misaligned triangular optical cavity

$$\Delta z_a = \Delta z_c = \Delta z_w = \beta_{\text{eff}} \cdot (R - L) = \beta_+ \cdot (R - L) / \sqrt{2}$$
(61)

$$\Delta z_b = \beta_{\text{eff}} \cdot R = \beta_+ \cdot R / \sqrt{2} \tag{62}$$

To summarize, a misalignment in $+(-)\beta_+$ causes a counter-clockwise (clockwise) tilt of the geometrical axis of the two flat mirrors around the center of curvature. As a result the plane of the eigenmode tilts synchronously.

4.3. Misalignment in β_{-}

Here, mirrors M_a and M_c rotate around the y_a and y_c -axis by $\pm 1/2 \beta_-$, respectively, as shown in Fig. 20. When the two opposite misalignment angles on mirrors M_a and M_c are projected onto

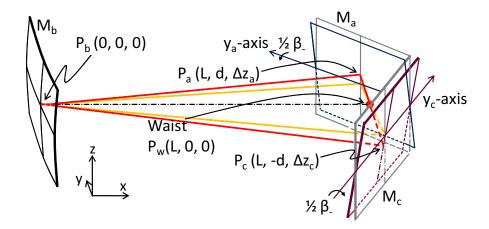


Figure 20. Cavity eigenmodes of the aligned and the misaligned (β_{-}) cases. The beam spot position and the waist position stays unchanged.

the x-z plane, they appear as rotations around the y-axis by $\pm \frac{\beta_{\rm eff}}{2}$, respectively, yielding no change along the z-axis on the curved mirror M_b . On the other hand, when they are projected onto the y-z plane, as shown in Fig. 21, they both appear as rotations around the z-axis by $\beta_{\rm eff}/2$, yielding shifts along the z-axis in the beam spot positions on the two flat mirrors by the same amount, but with opposite sign. Note that here $\beta_{\rm eff} \equiv \beta_-/\sqrt{2}$. These spot position changes are symmetrical along the y-axis, thus they do not yield a change in the beam spot position on the curved mirror along the y-axis, nor a change in the waist position (which is equidistant from the two spot positions) along the y-axis and x-axis. Hence the spot on the curved mirror and the waist remain unchanged, indicating that the new eigenmode is formed by rotating the aligned eigenmode around the x-axis by θ , yielding no change in the lengths on any sides of the triangle.

The inclination angle of the beam between the two flat mirrors with respect to the x-y plane is denoted by θ in Fig. 21. Focusing on the isosceles triangle as indicated by the shaded triangle in the figure, whose equal angles are denoted as μ , the inclination angle is given by the following equations:

$$\mu = \pi/2 - \beta_{\text{eff}}/2 \tag{63}$$

$$\theta = \pi - 2\mu = \beta_{\text{eff}} \tag{64}$$

Therefore the beam spot position shifts on the two mirrors are calculated to be

$$\Delta z_a = -\Delta z_c = d \cdot \alpha_{\text{eff}} = d \cdot \beta_- / \sqrt{2}$$
 (65)

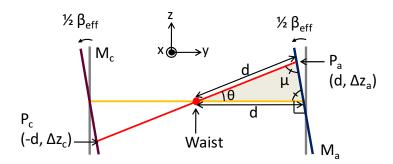


Figure 21. Projection of the triangular cavity onto the y-z plane. The plane of the cavity is rotated around the x-axis by θ , however the lengths of all the sides of the triangle remain unchanged.

To summarize, a misalignment in $+(-)\beta_{-}$ causes no change in the spot position on the curved mirror and a counter-clockwise (clockwise) rotation of the non-congruent side around the x-axis. As a result, the plane of the eigenmode rotates synchronously.

5. Result and comparison

Tables 2 and 3 show the results from the geometrical analysis, and compare them to the simulation results obtained by using two simulation tools. One is OptoCad [4] and the other is IfoCad [5]. We used them to trace the Gaussian beam through our triangular cavity model that has the design parameters for the AEI 10 m Prototype reference cavity. These parameters are given as follows: $R = 37.8 \, m$, $L = 10.05 \, m$, and $d = 0.15 \, m$. By inserting these values into our geometrical model, we obtained the corresponding numerical values. Due to the fact that OptoCad is 2-dimensional we only used it for simulating the horizontal misalignment types.

6. Conclusion

The results of the geometrical analysis are in excellent agreement with the simulation results, showing sufficient accuracy for the design of an alignment control system for a triangular cavity. We have checked that all the discrepancies between the geometrical analysis and the simulations decrease by assigning real values for the two larger angles γ to the geometrical analysis, instead of using $\gamma = \pi/2$. This analysis can easily be extended to a cavity with more general shape if one follows the equations derived in this paper and modifies the method of approximation properly. The geometrical analysis not only serves as a method of checking a simulation result, but also gives an intuitive and handy tool to visualize the eigenmode of a misaligned triangular cavity.

7. Acknowledgments

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Waist Type Method ${\rm M_b}$ $M_{\rm a}$ $M_{\rm c}$ Δy $\Delta y \ \Delta x$ Δy Δx Angle Δx Δx Δy Geom. Analy. -0.205-0.2050.2050.205-0.2050 -13.9700 -1.370OPTOCAD -0.202-0.206-0.2020 - 13.9740.209-1.3700.2060 α_b IFOCAD 0.205-0.202-0.205-0.2020 - 13.9740.209-1.3700 0 Geom. Analy. -10.05110.051 -10.0510 0 - 10.051-10.051OPTOCAD -10.051 0 - 10.0510 0 9.902-10.051-9.9020 α_{-} IFOCAD -10.051 9.903 - 10.051-9.903 0 0 - 9.90220 0 Geom. Analy. 0 -0.001 1.005 -0.1510.1510.1510.1510 0.205OPTOCAD -0.1510.1490.1510.1490 0.206 0 - 0.0031.005 α_{+} IFOCAD -0.1510.1490.151 0.1490 0.2050 - 0.0031.005

Table 2. Horizontal misalignment comparison.

Table 3. Vertical misalignment comparison.

Type	Method		M_{a}		M_c		$M_{\rm b}$		Waist	
0 1		Δx	Δz	Δx	Δz	Δx	Δz	Δx	Δz	Angle
β_b	Geom.Analy.	0	37.800	0	37.800	0	37.800	0	37.800	0
	IFOCAD	0	37.800	0	37.800	0	37.800	0	37.800	0
β_{-}	Geom. Analy.	0	0.106	0	-0.106	0	0	0	0	0.707
	Ifocad	0	0.106	0	-0.106	0	0	0	0	0.702
β_{+}	Geom.Analy.	0	-19.622	0	-19.622	0	-26.729	0	-19.622	0
	IFOCAD	0	-19.770	0	-19.770	0	-26.930	0	-19.770	0

References

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 Simulation tool http://www.rzg.mpg.de/~ros/optocad.html
- [5] IFOCAD 2010 A framework of C subroutines to plan and optimize the geometry of laser interferometers, written by Gerhard Heinzel Simulation tool